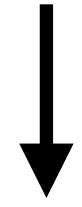


Regression and Image Restoration

Image based ML Tasks

Classification

$$\mathbb{R}^N$$



Cat, Dog, ...

$$[1, \dots, K]$$

Detection/Segmentation

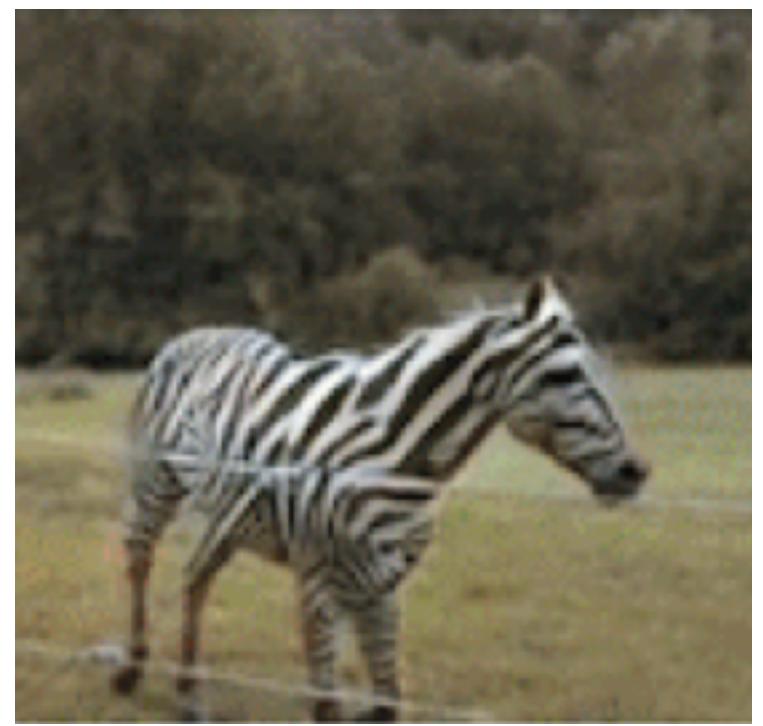
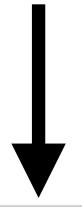
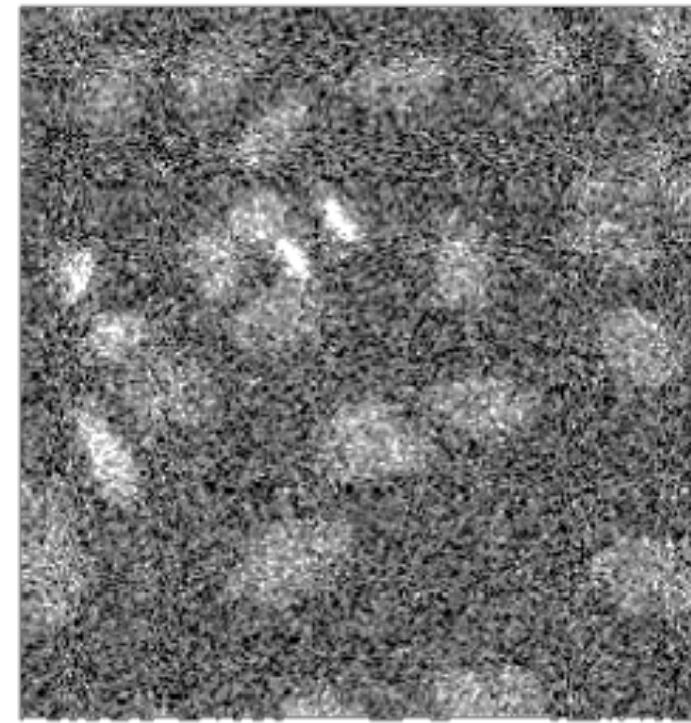
$$\mathbb{R}^N$$



$$[1, \dots, K]^N$$

(Dense) Regression

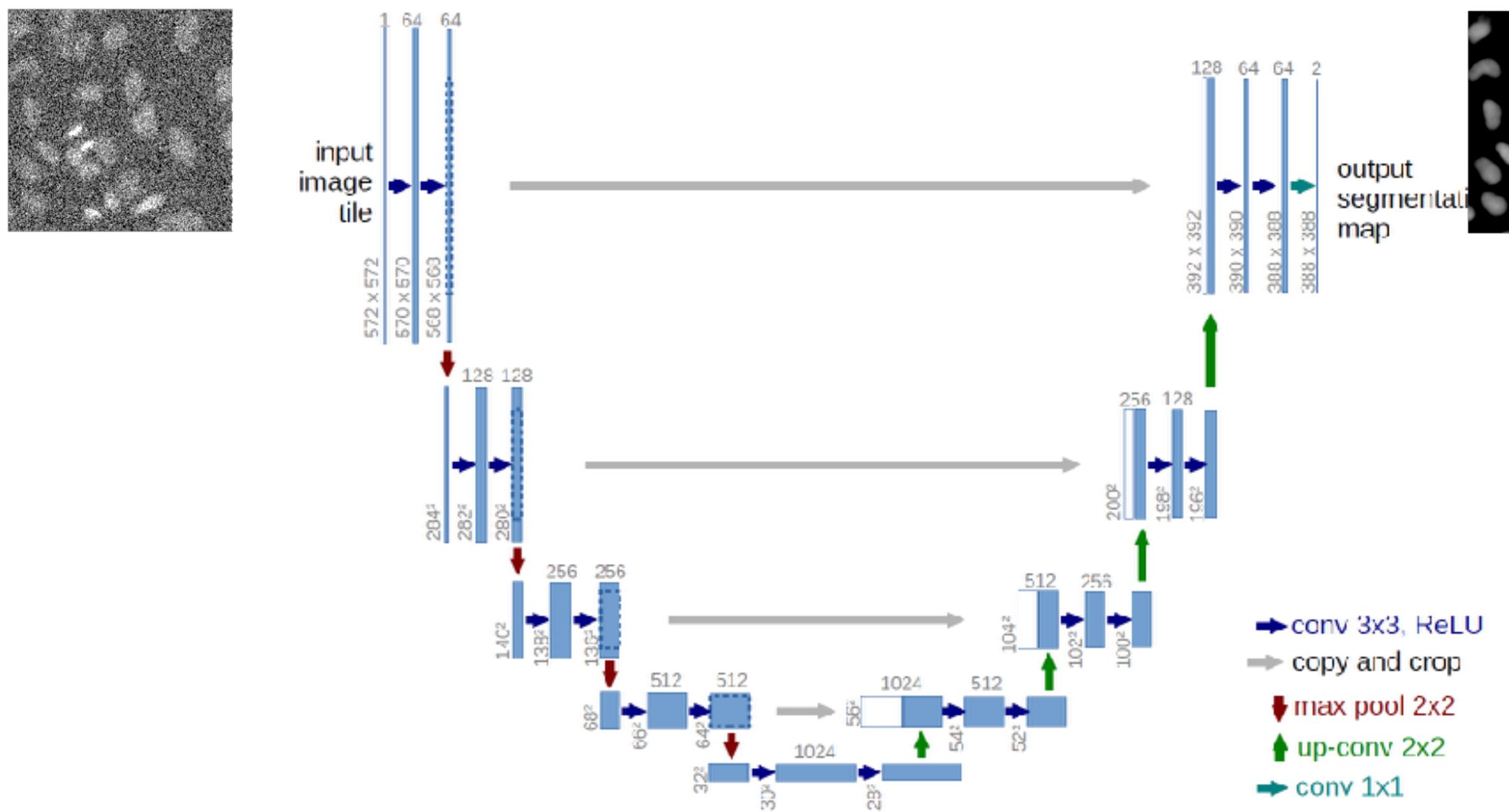
$$\mathbb{R}^N$$



$$\mathbb{R}^N$$

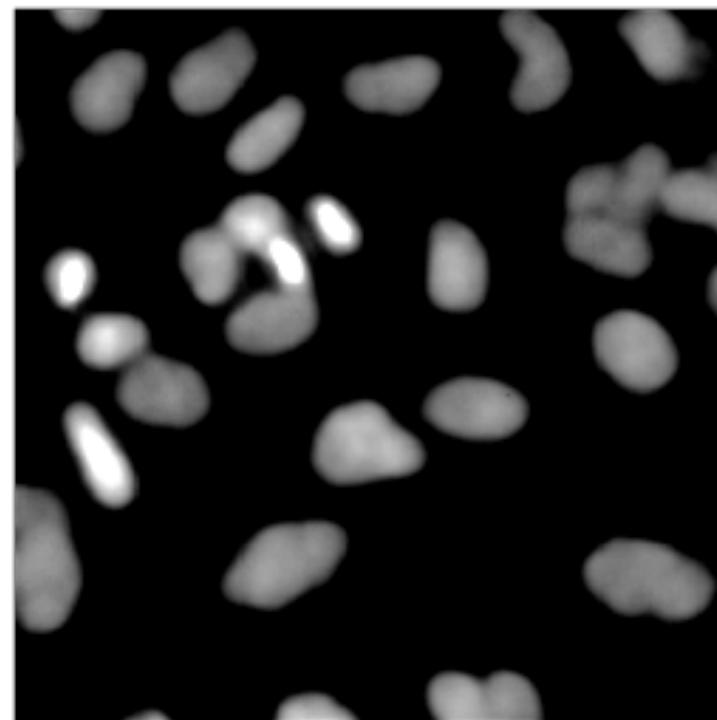
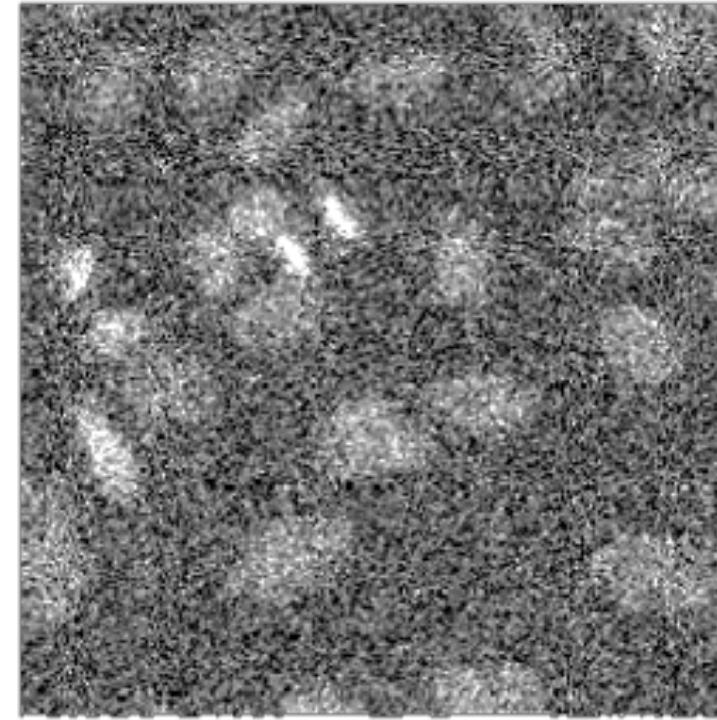
(Dense) Regression

- Input and Output are real valued images (or scalars, sequences)
- We can use almost the same architectures as for dense segmentation, only have to change last activation function (e.g. linear, instead of sigmoid/softmax)



(Dense) Regression

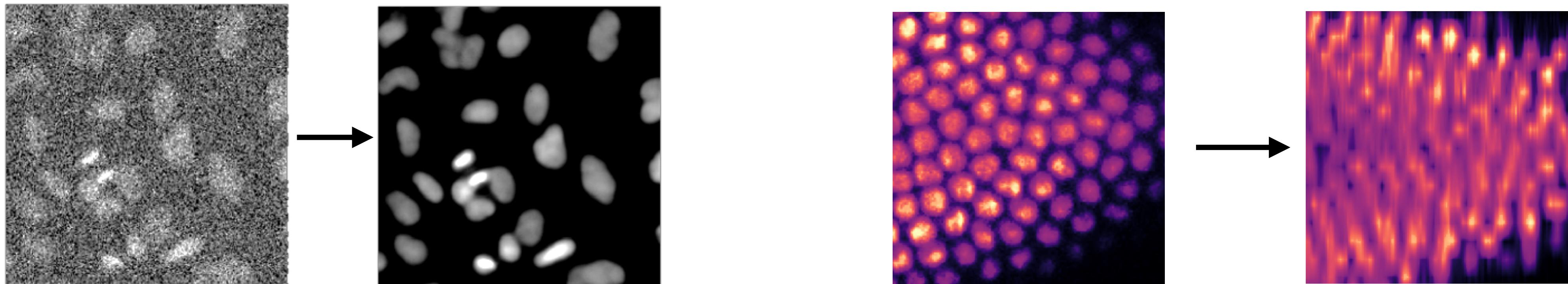
\mathbb{R}^N



\mathbb{R}^N

Examples - Image Restoration

- Denoising, Upsampling (Mao 2016, CARE 2017)
- typically with pixel-wise loss, e.g. mean squared error (MSE, L2) $\frac{1}{N} \sum_{i=1}^N \|\tilde{y}_i - y_i\|^2$ or mean absolute error (MAE, L1)



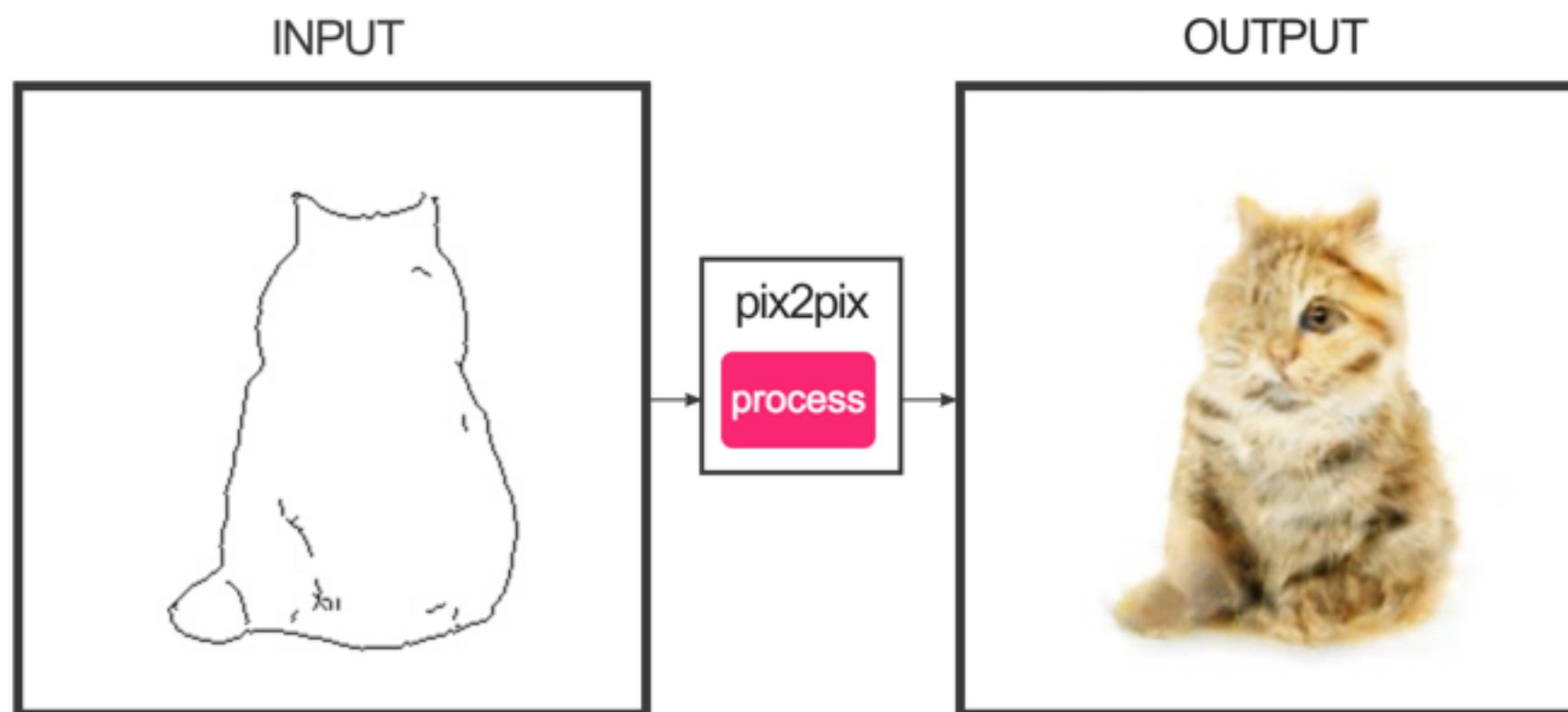
Examples - Style Transfer

- E.g. Gatys 2016, Johnson 2016
- Perceptual loss: Compare intermediate feature responses of a classification network



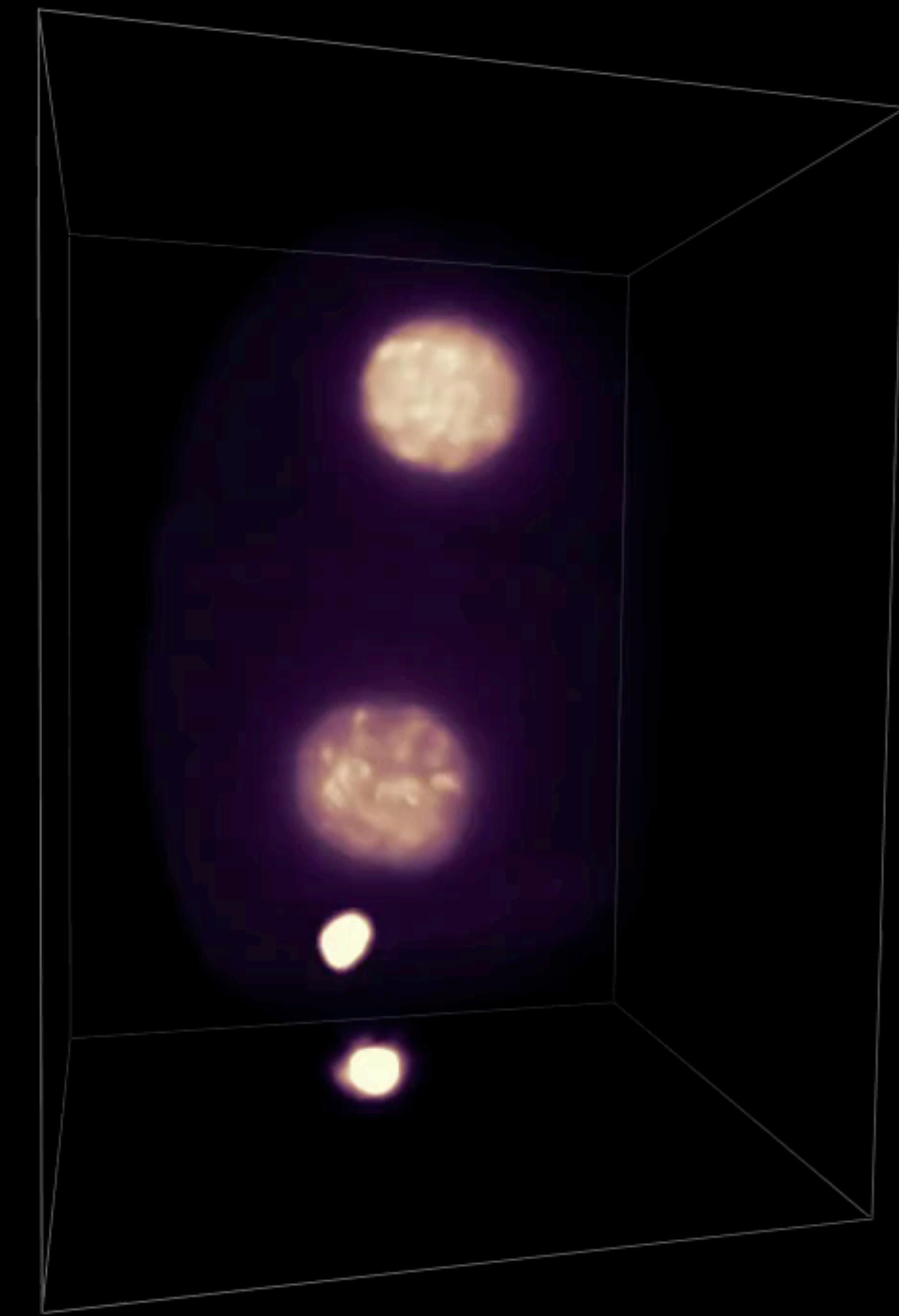
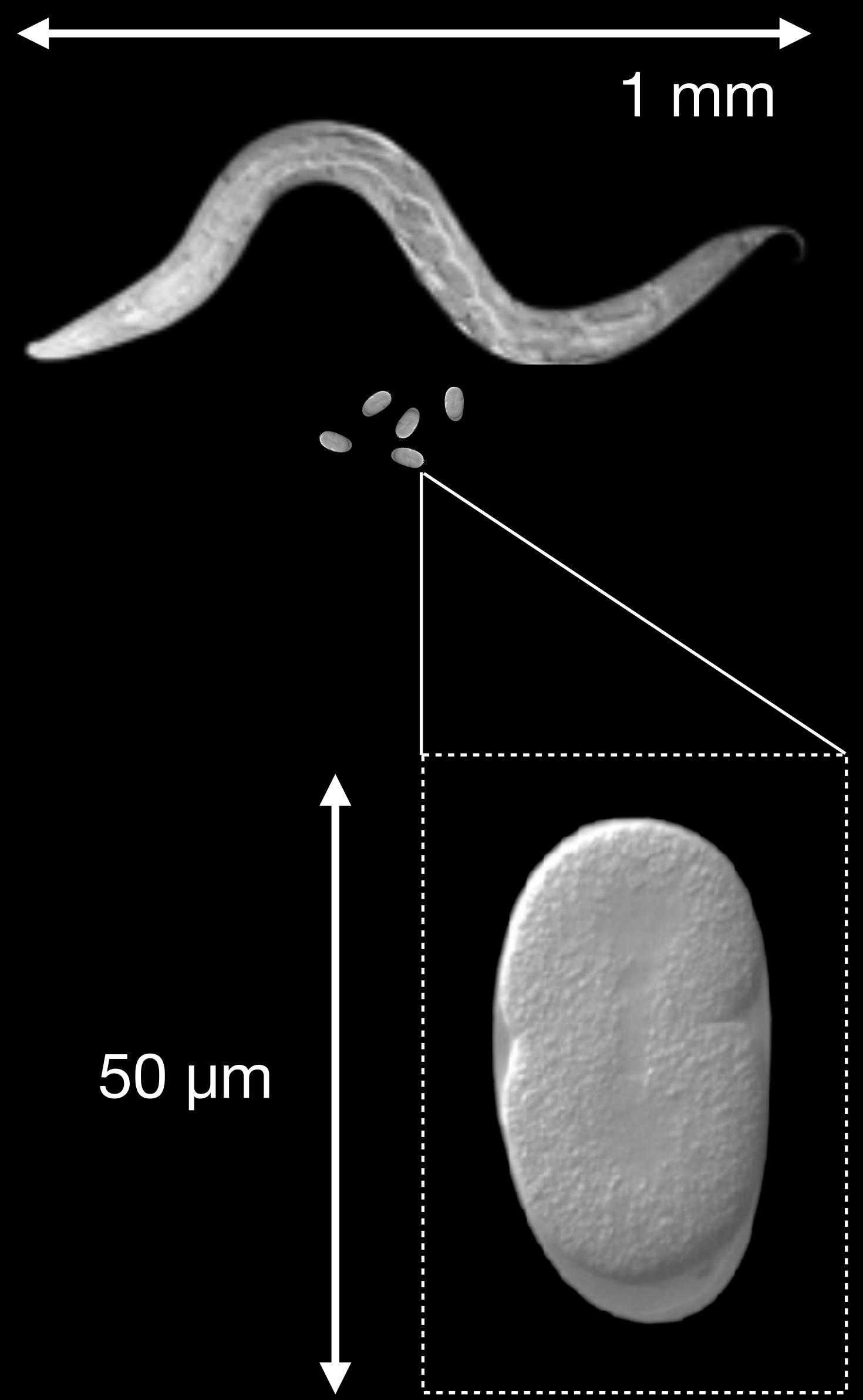
Examples - Image2Image Translation

- E.g. pix2pix (Isola 2017), CycleGAN (Zhu/Park 2016)
- Adversarial loss: Using a discriminator (cf GANs)

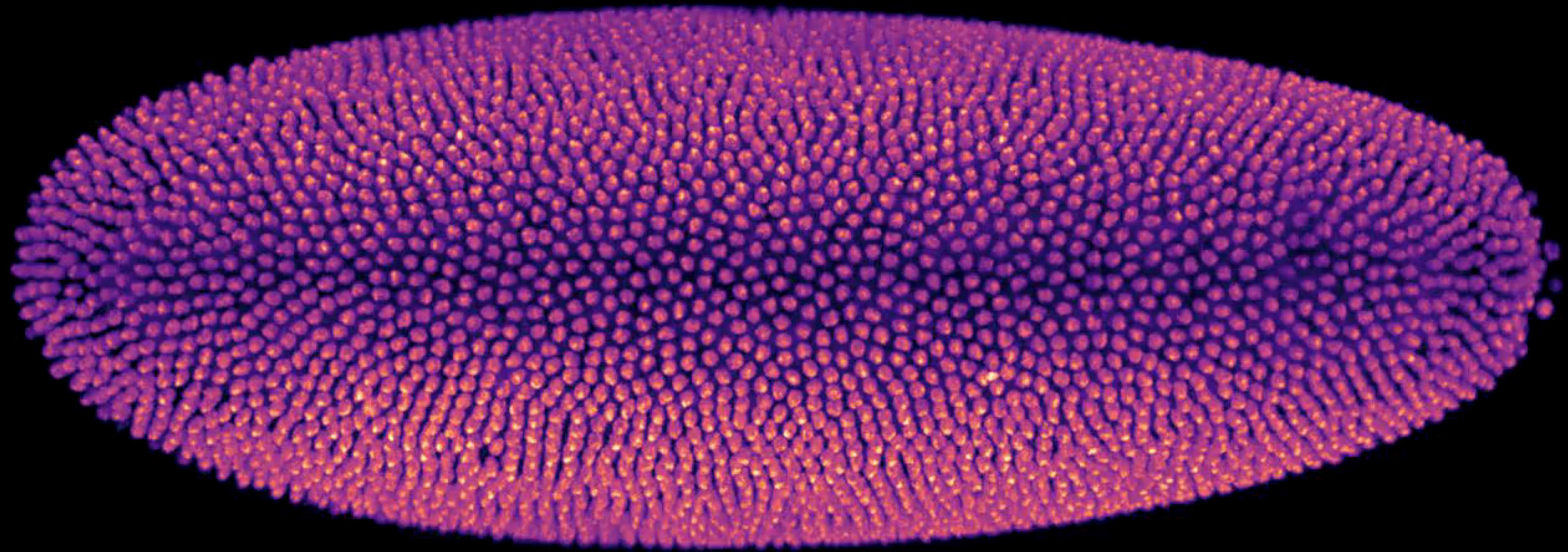
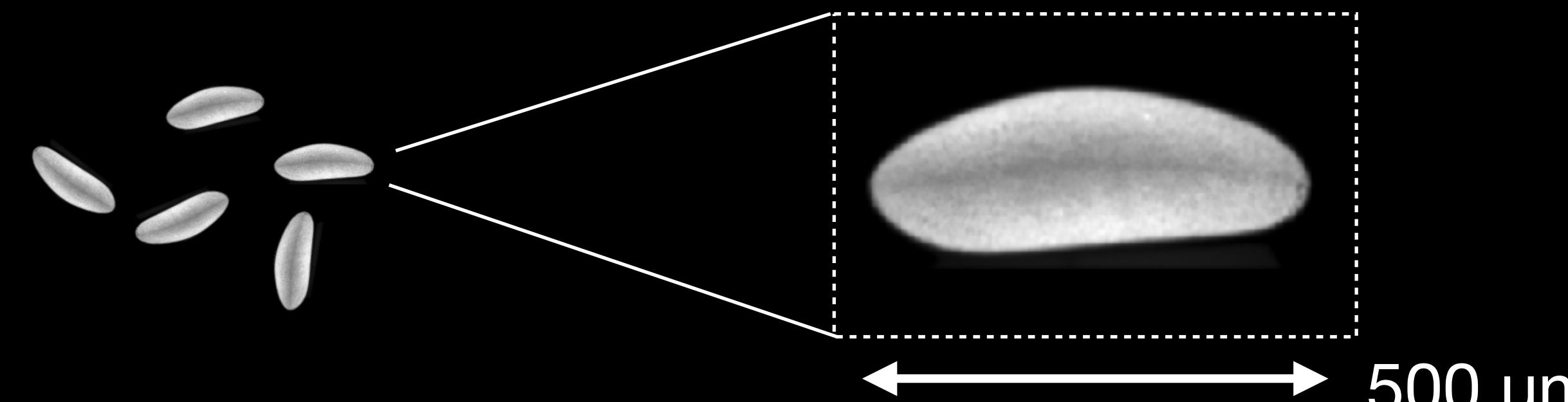


<https://affinelayer.com/pixsrv/>

Case Study: Image Restoration for Fluorescence Microscopy

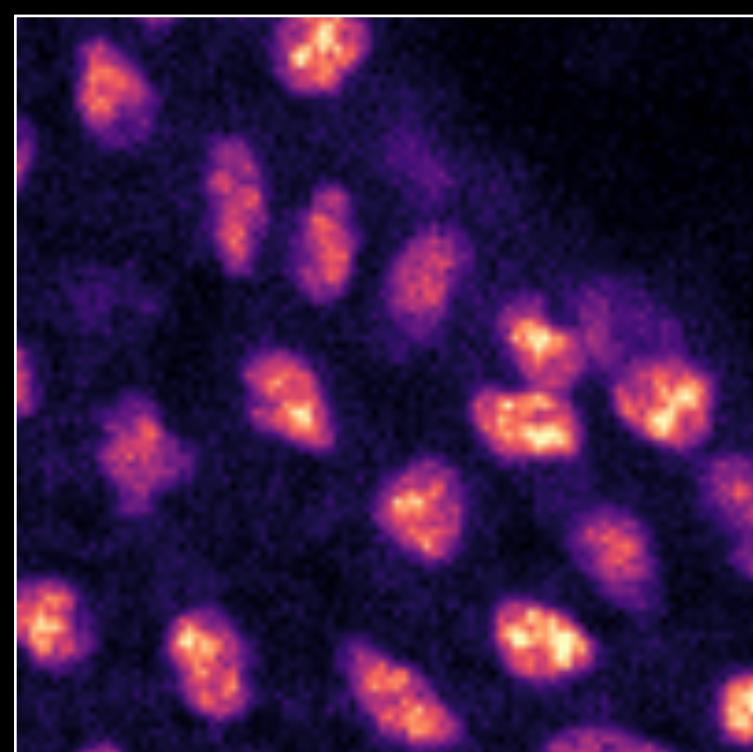


0:30:00

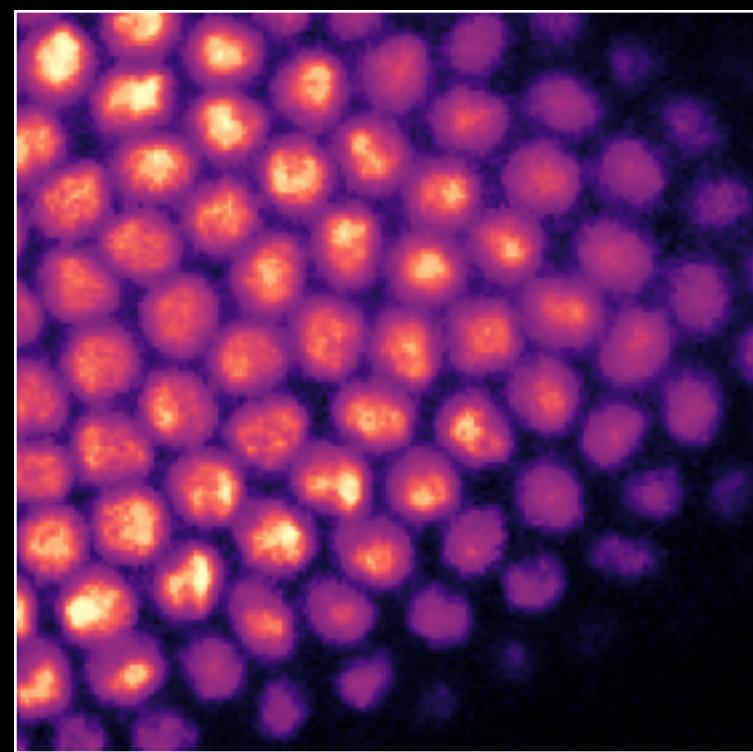
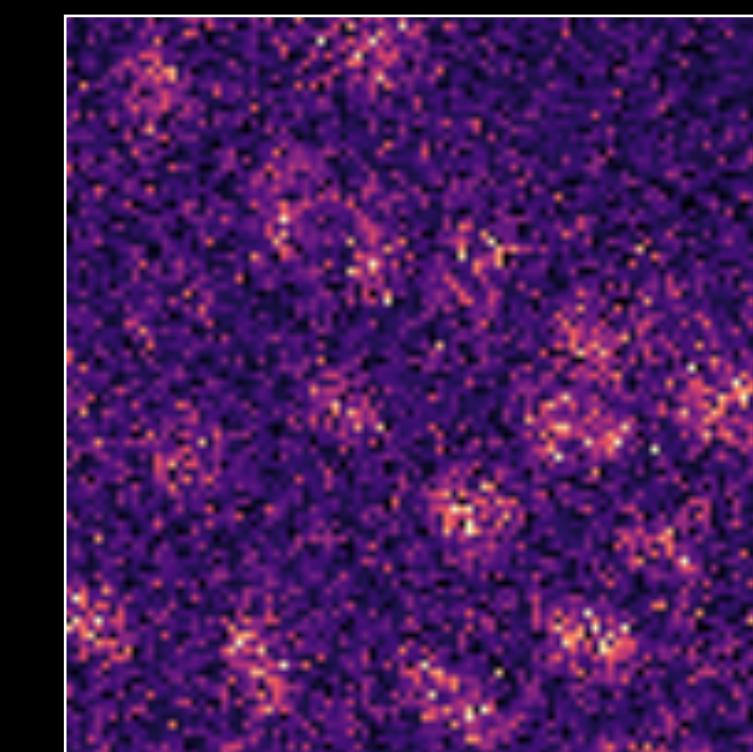


Loic Royer

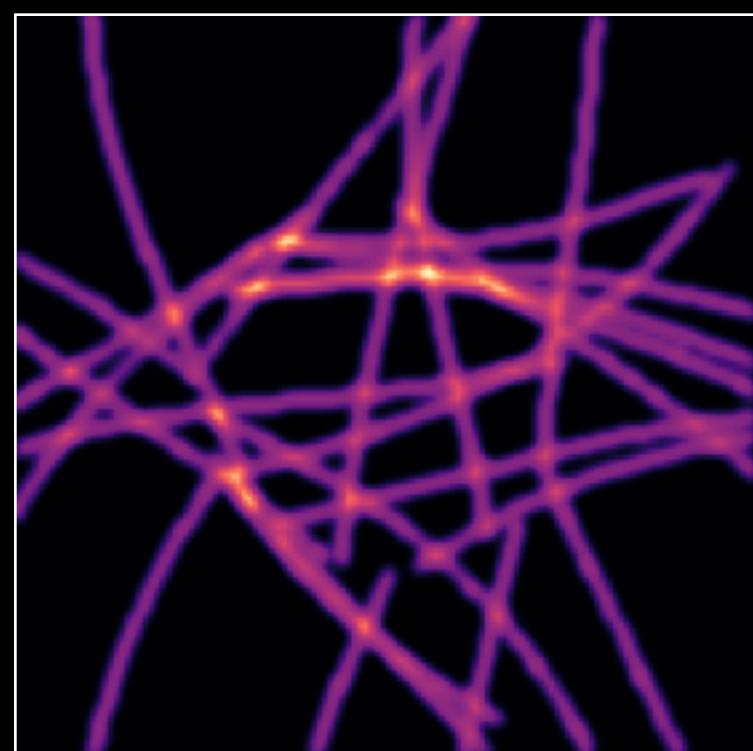
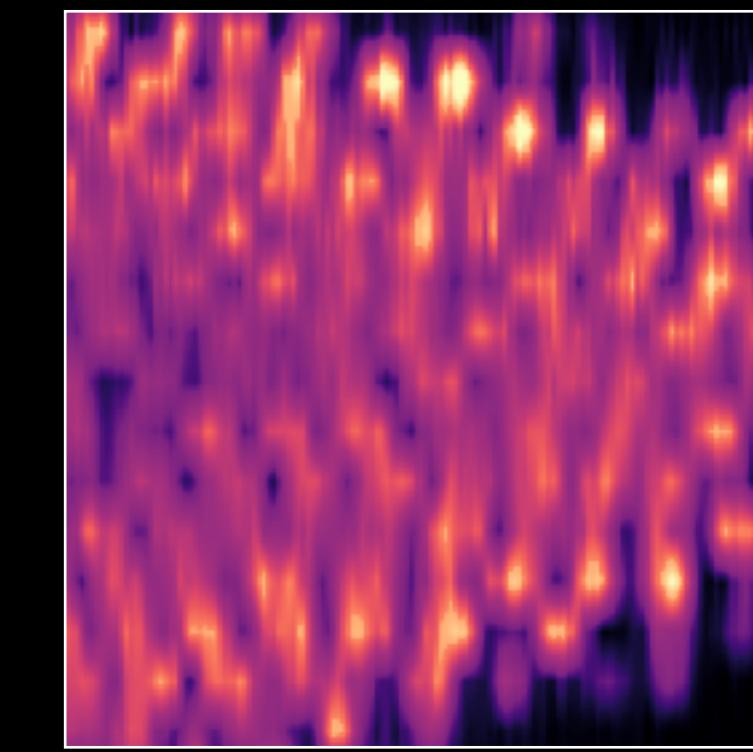
Image Restoration for Fluorescence Microscopy



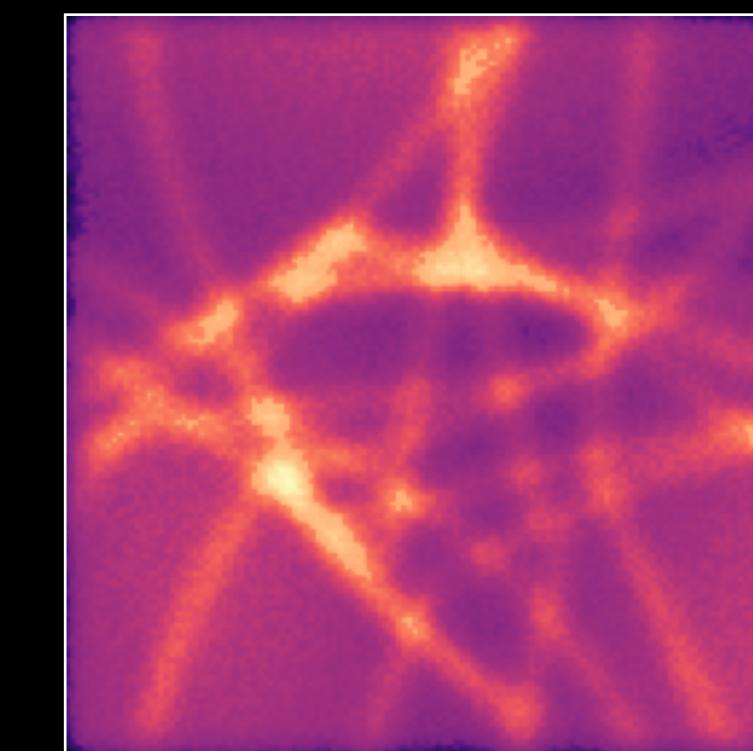
Denoising



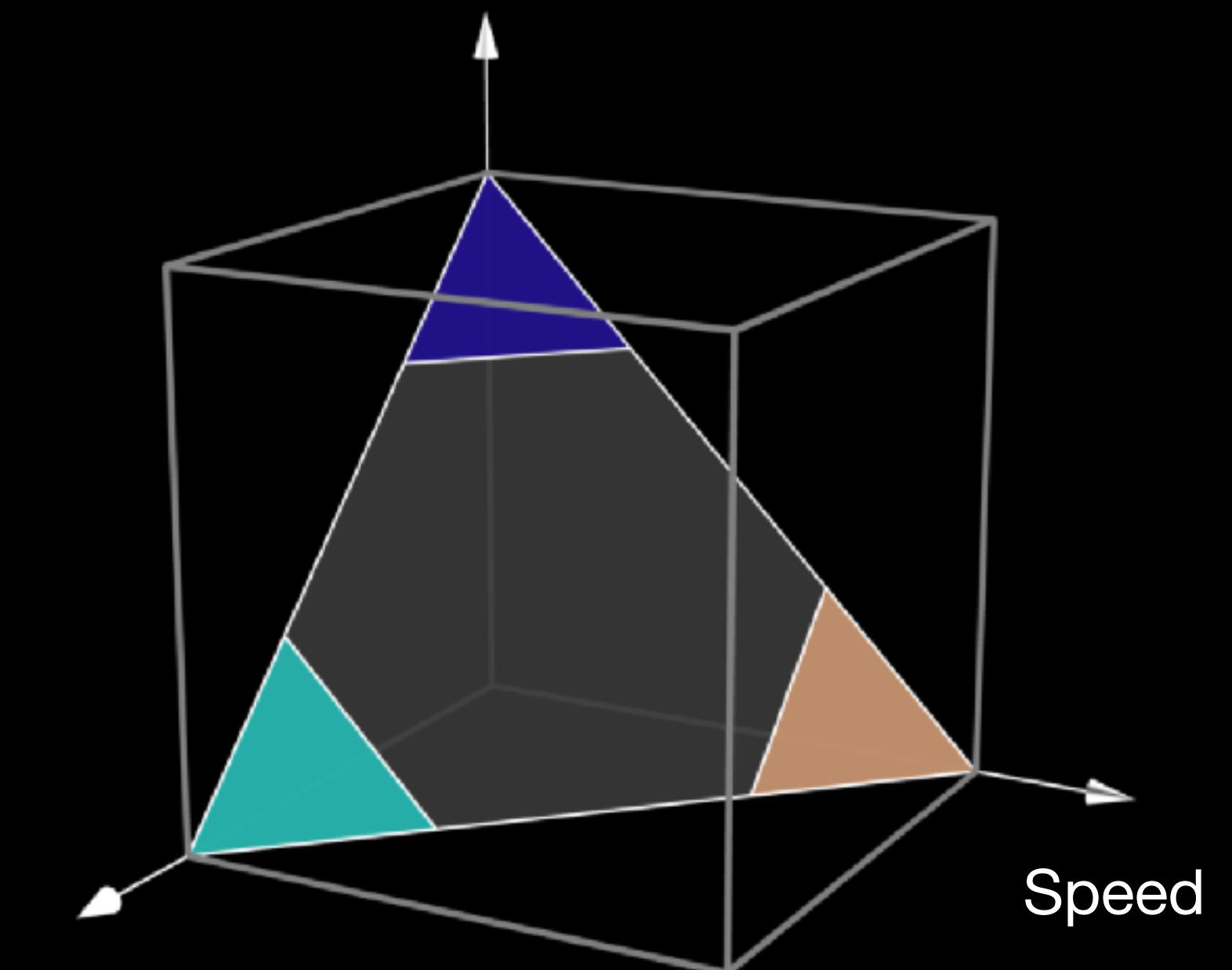
Upsampling



Deconvolution



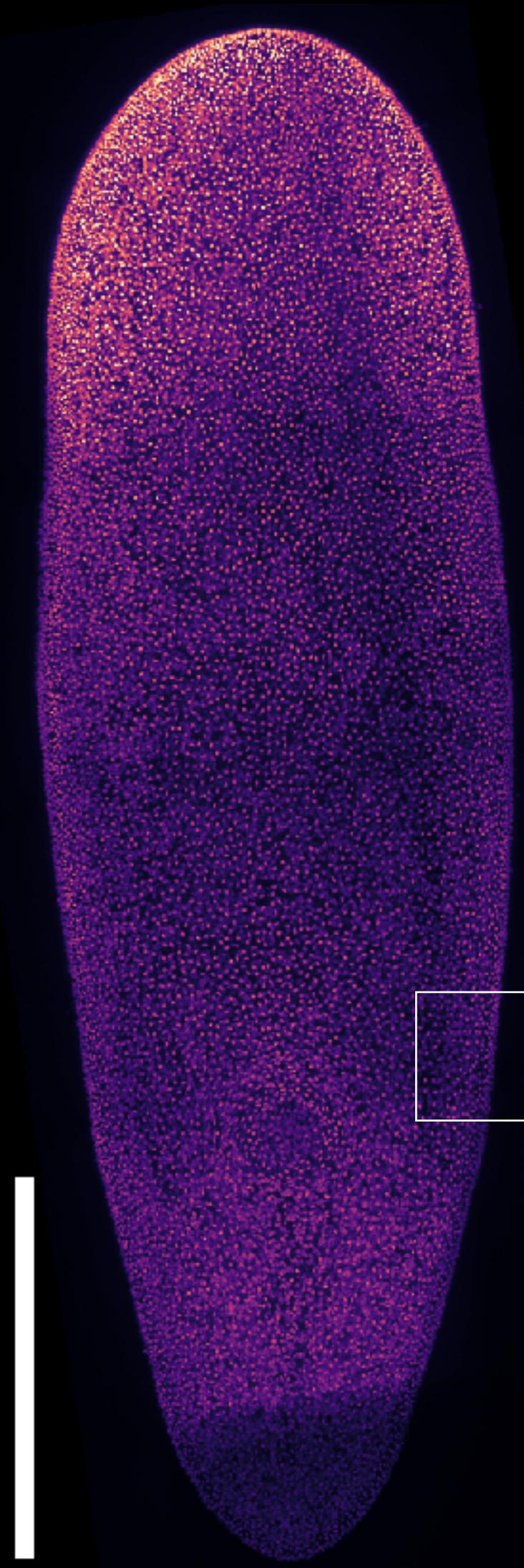
Light exposure



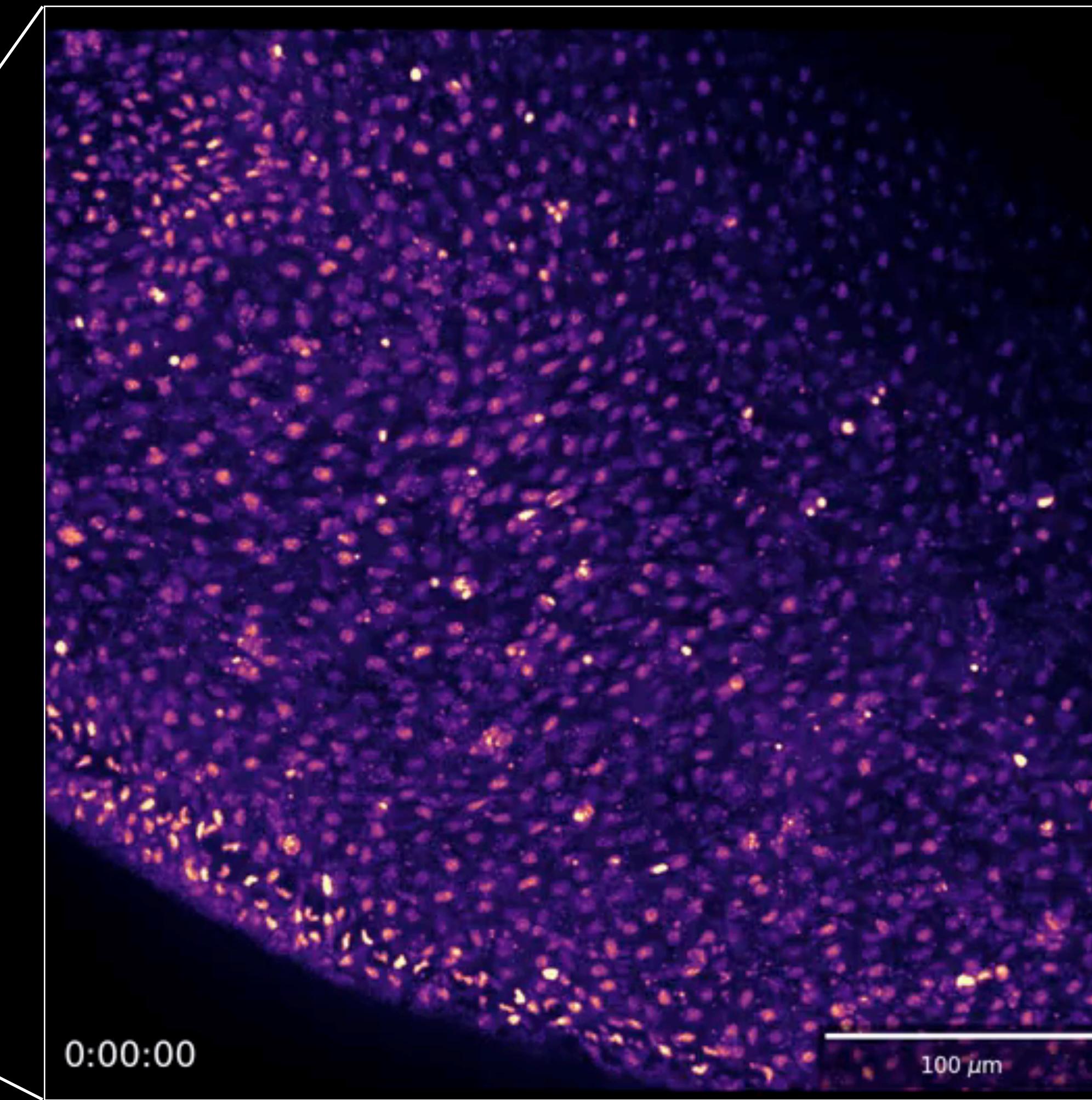
Spatial resolution

Imaging with low light

Planaria (Flatworm)

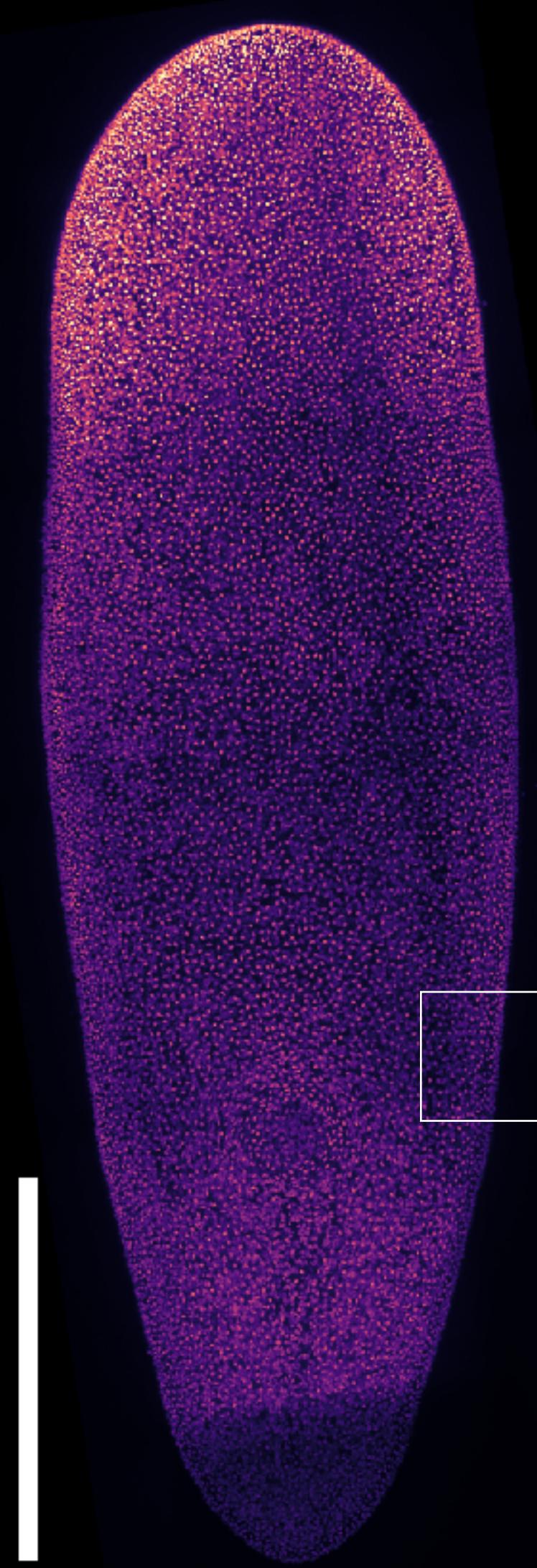


High light-dosage / High SNR

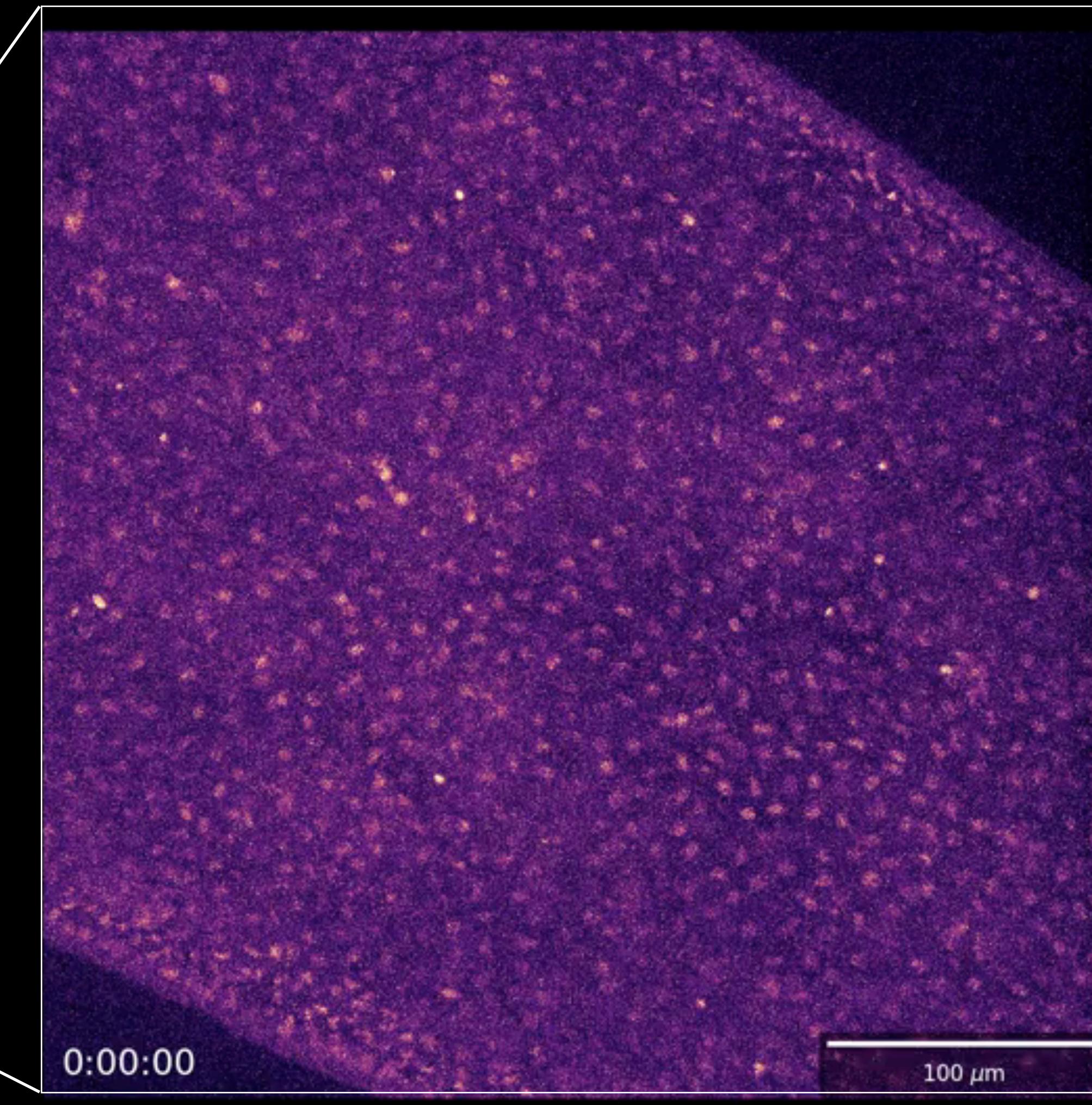


Imaging with low light

Planaria (Flatworm)

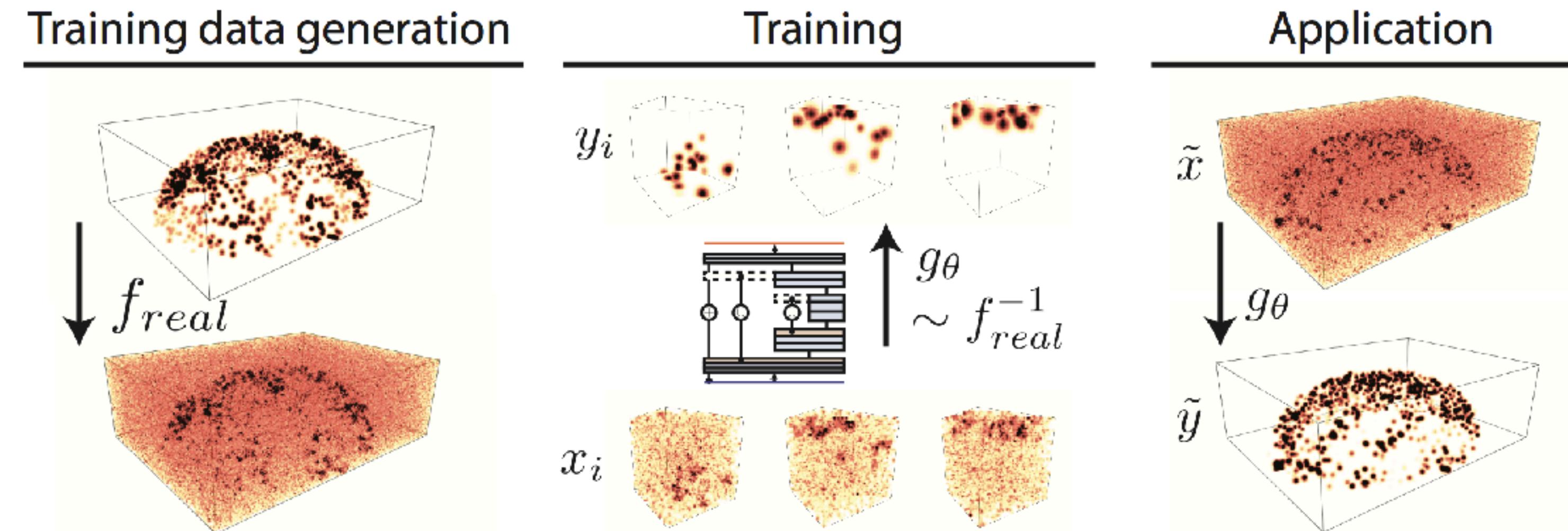


Low light dosage / low SNR



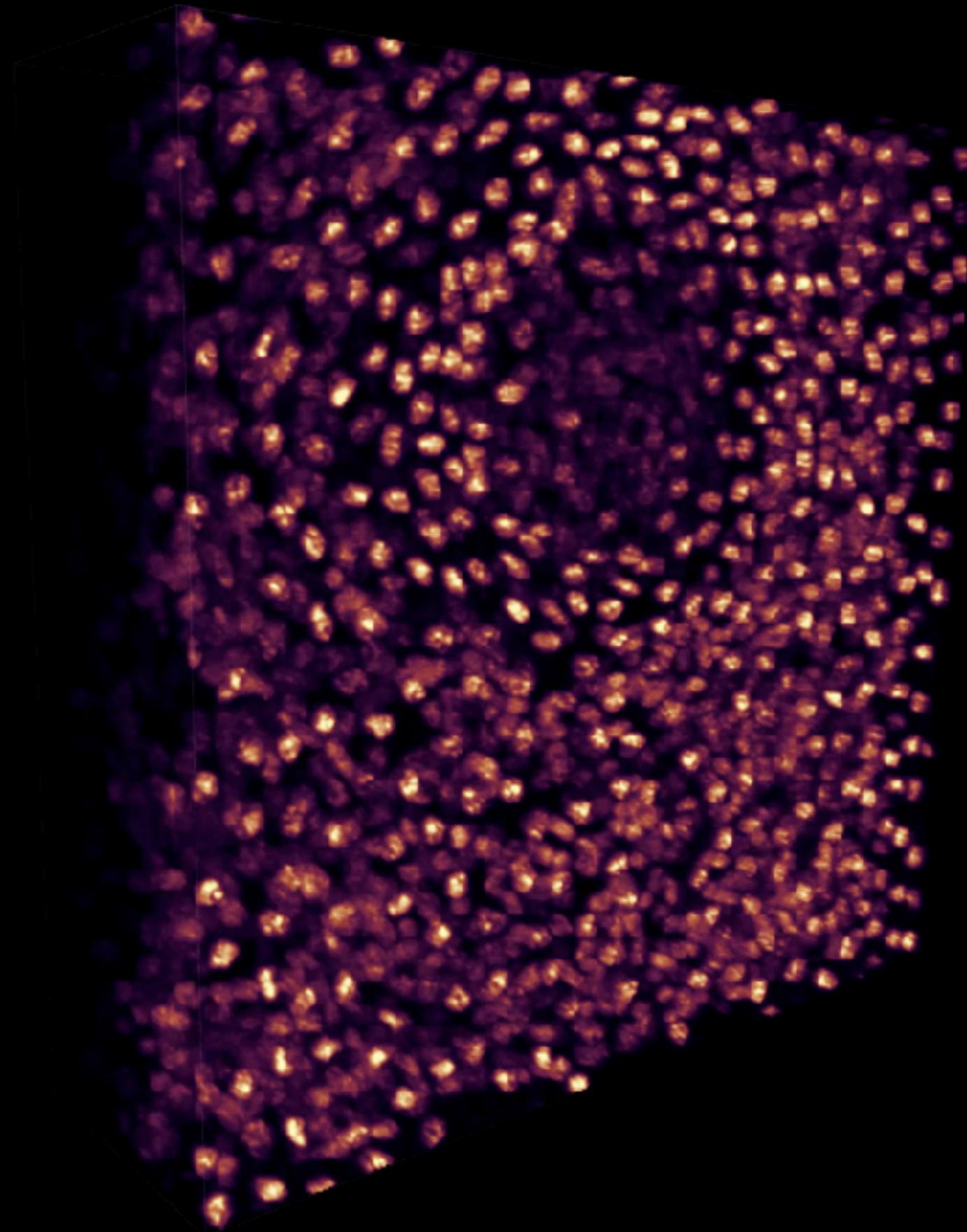
Content-Aware Image Restoration

- Supervised regression based on a specific experiment/organism/imaging modality
- Training data generation via physically acquired data, semi-synthetic imaging models, or fully-synthetic data
- Using simple but robust residual versions of the U-Net in 2D and 3D
- Trade training time for inference time (super fast!)
- Provide intuitive code for training data generation and network training -> CSBDeep

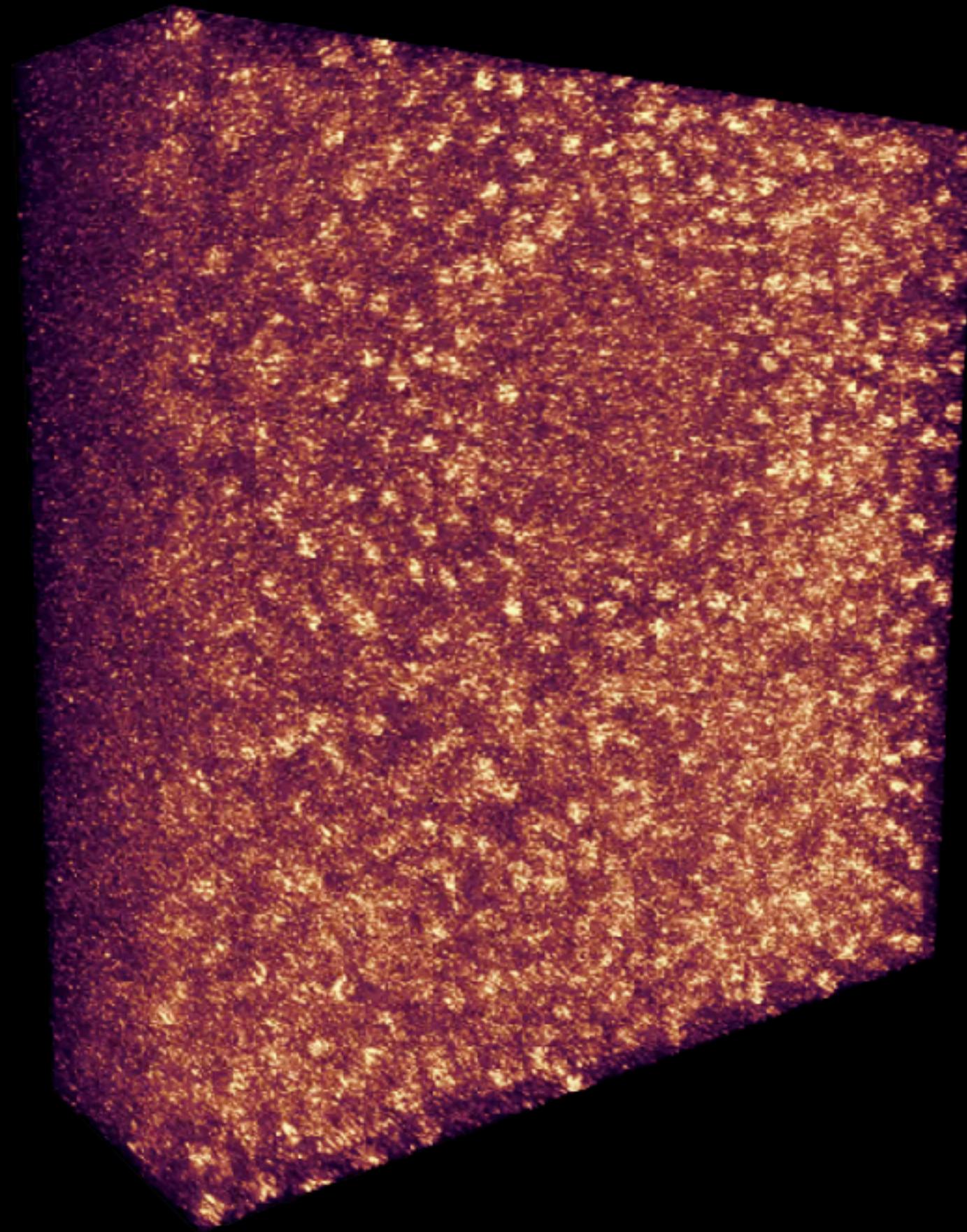


Imaging with low light

High

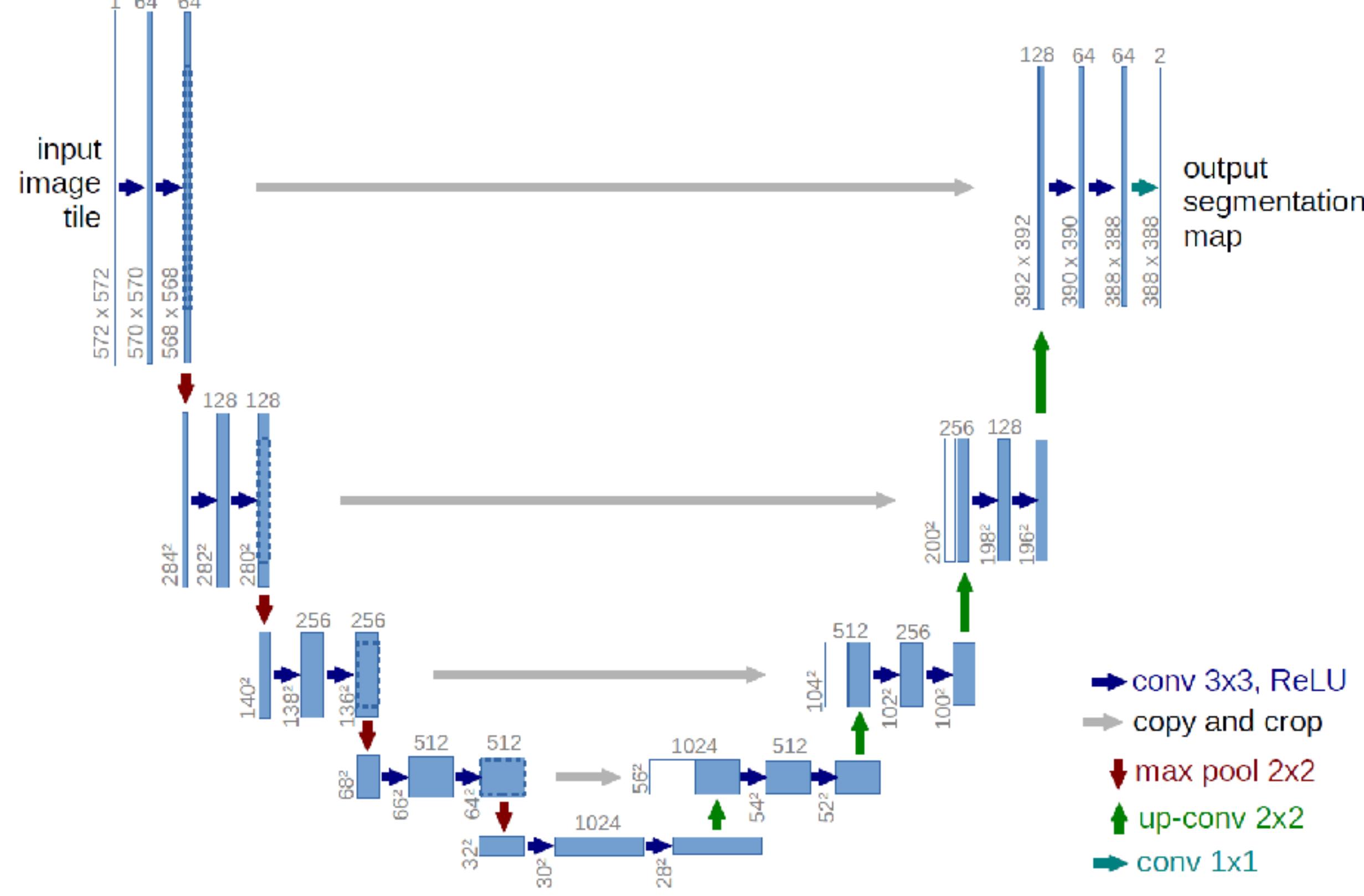
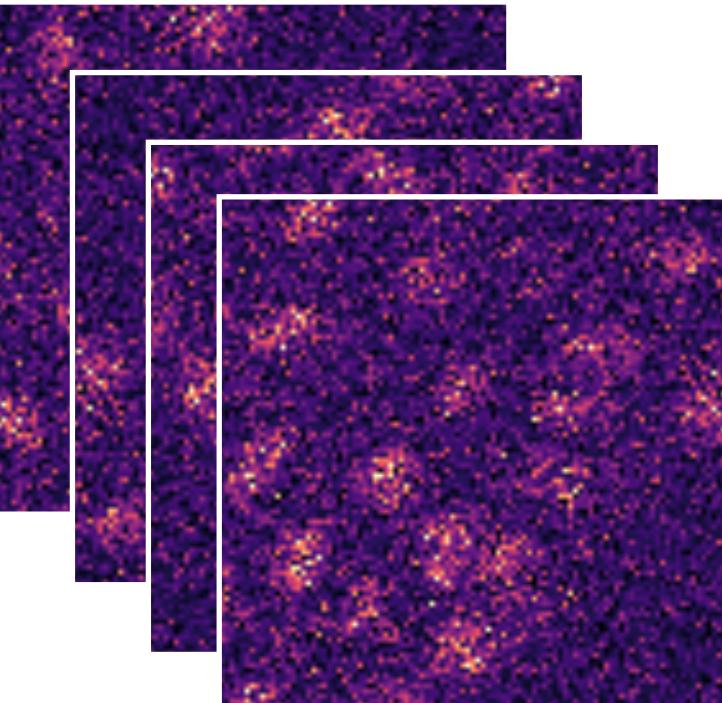


Low

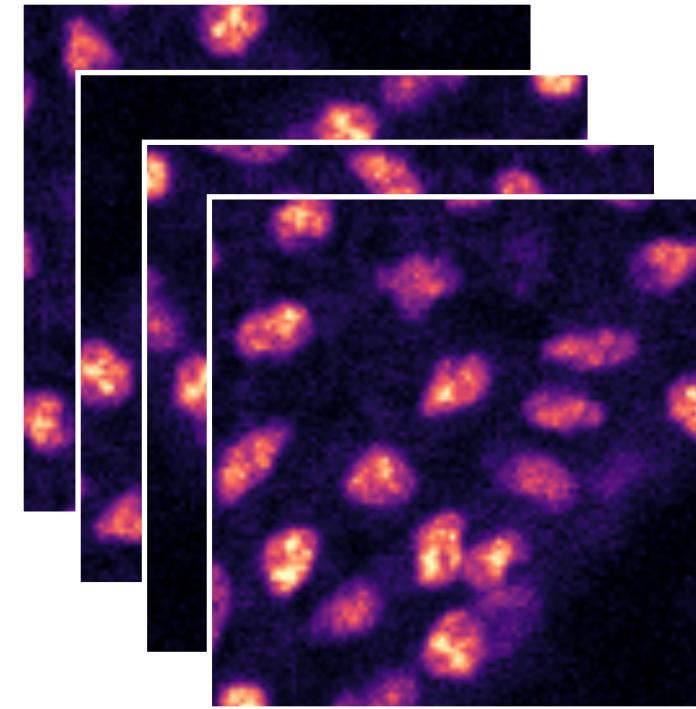


Imaging with low light

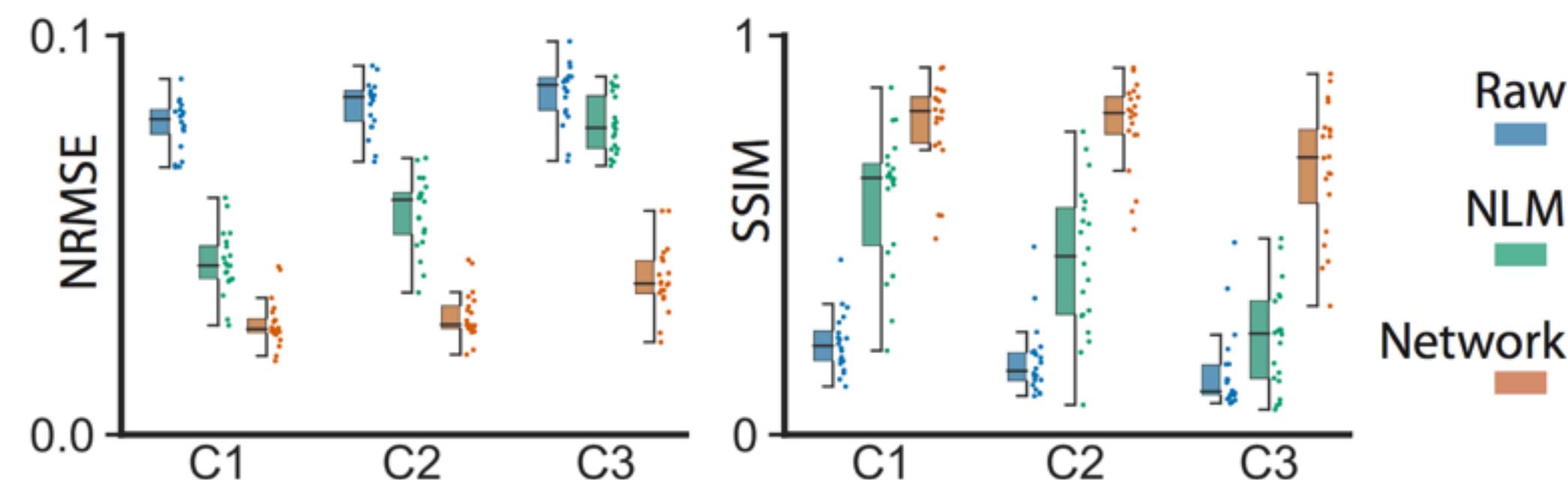
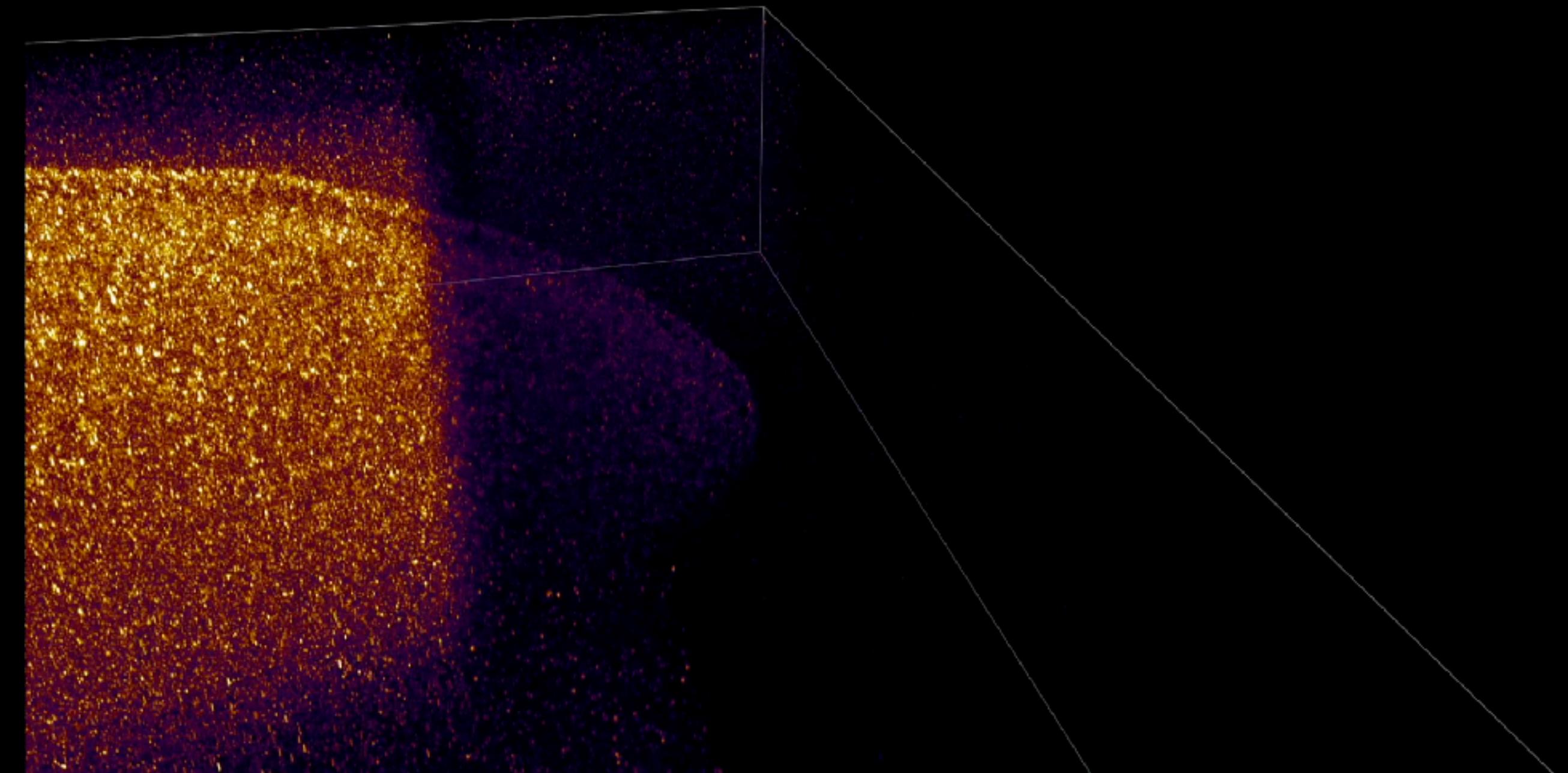
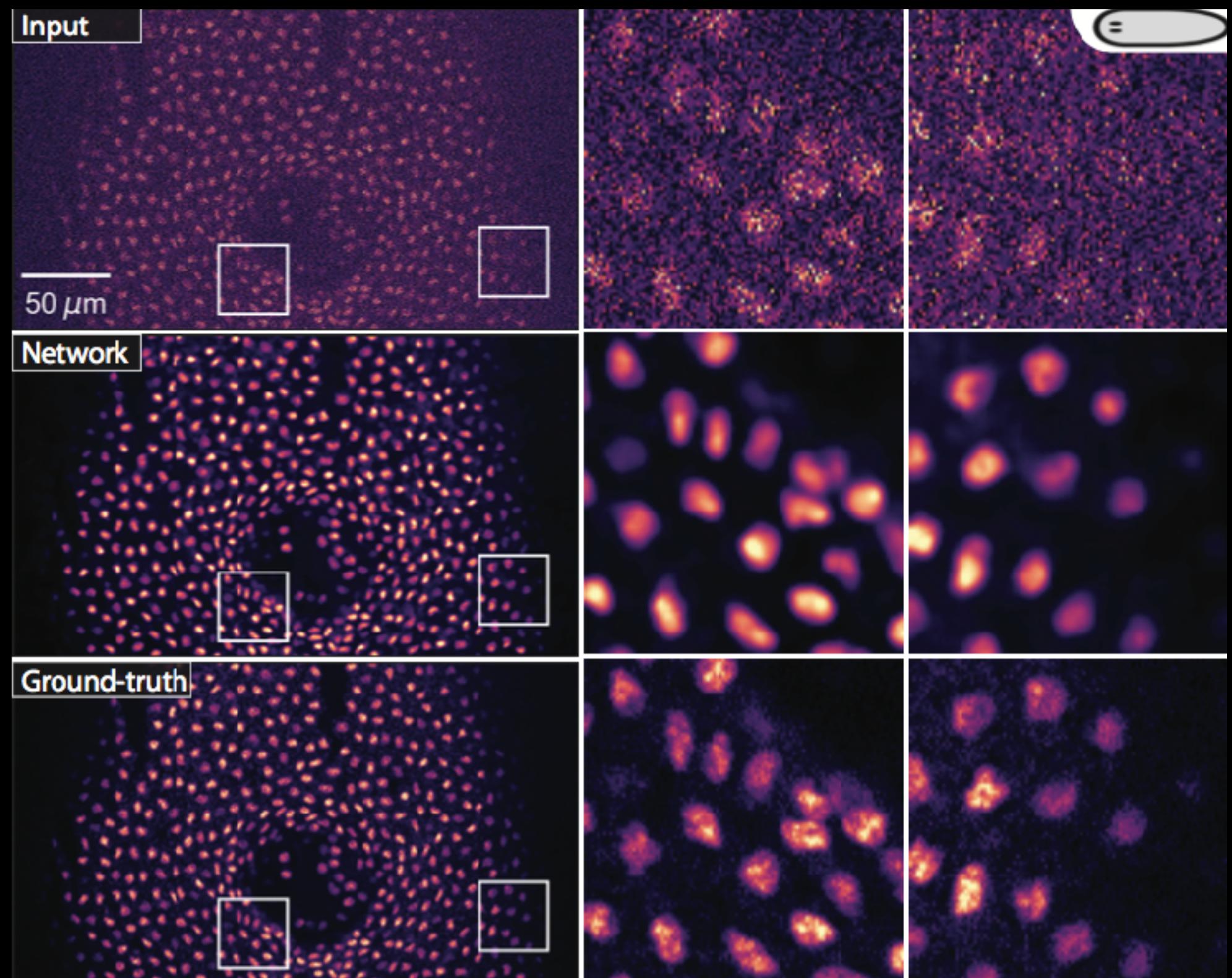
Low



High



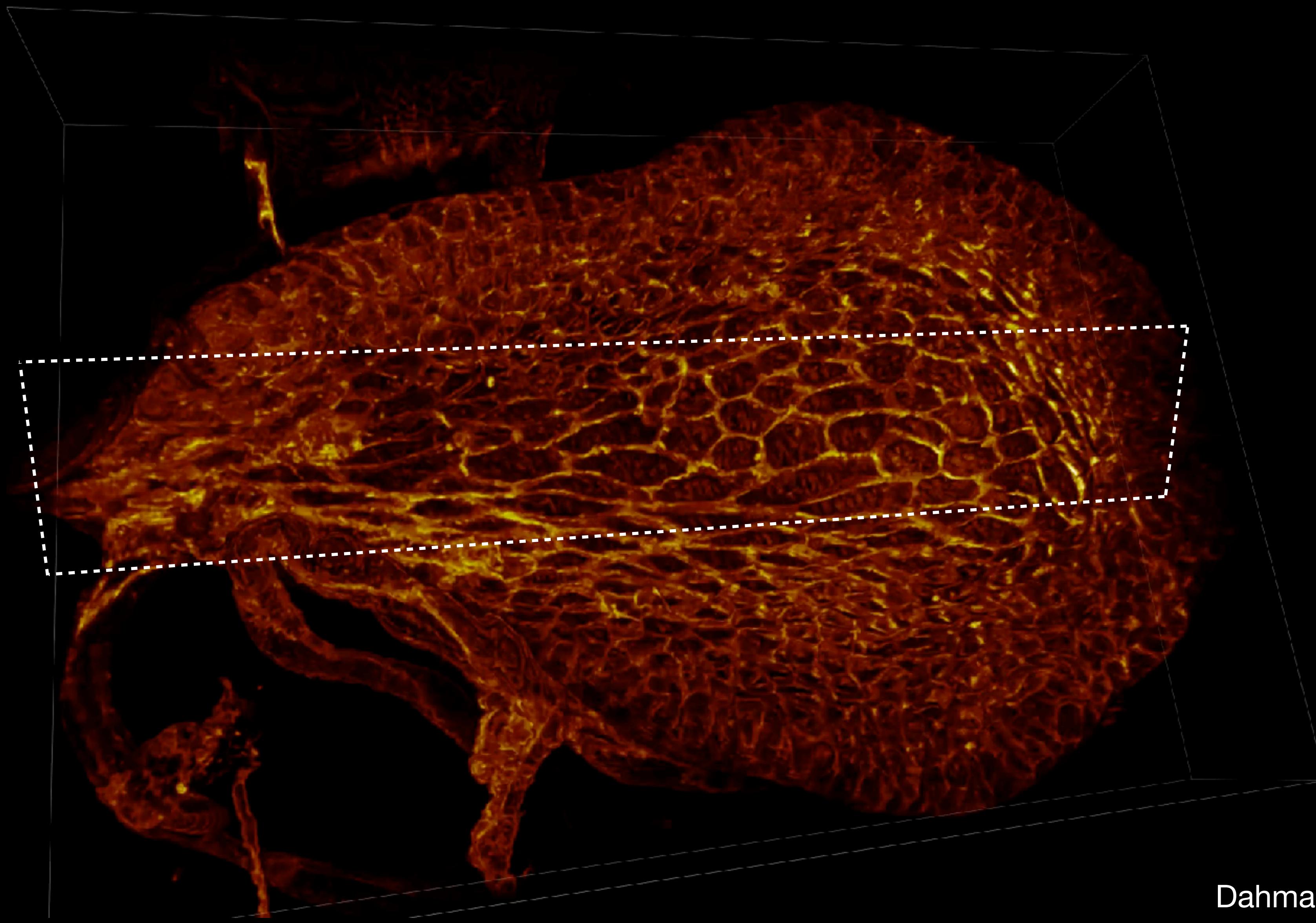
Imaging with low light



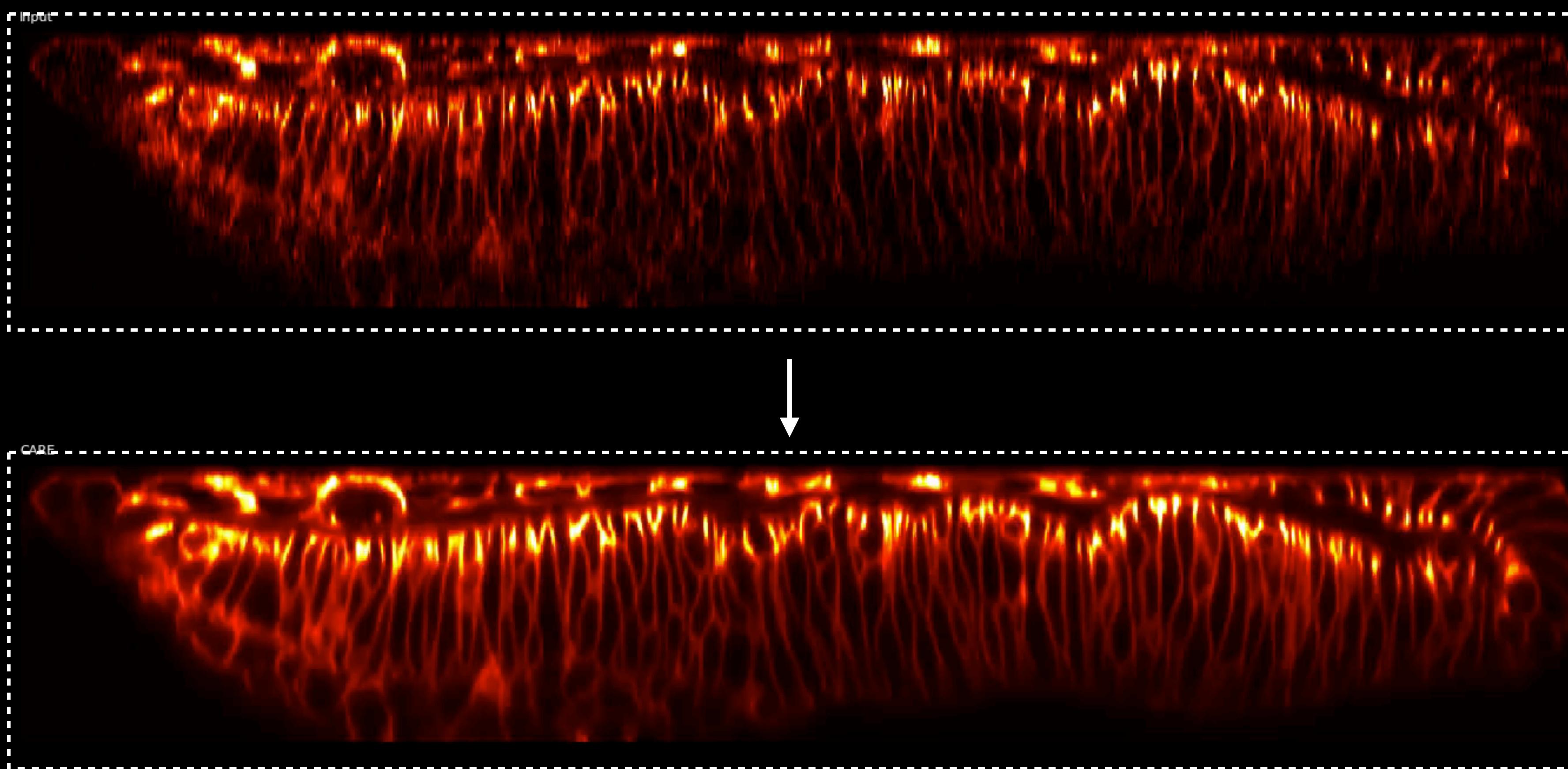
Challenges - Data Preprocessing and Normalisation

- All about getting good training data
- Typically >50% of all the work :)
- Dynamic range of network input should be $\sim (-1,1)$ or $(0,1)$
 - > We typically choose a robust percent normalisation of input/output images
- Domain Knowledge!
- Beware of outliers (e.g. hot pixels, detector read errors)
- Input-Output volumes have to be pixel-perfect registered, beware of sample movement, stage jittering, etc

Works for upsampling too



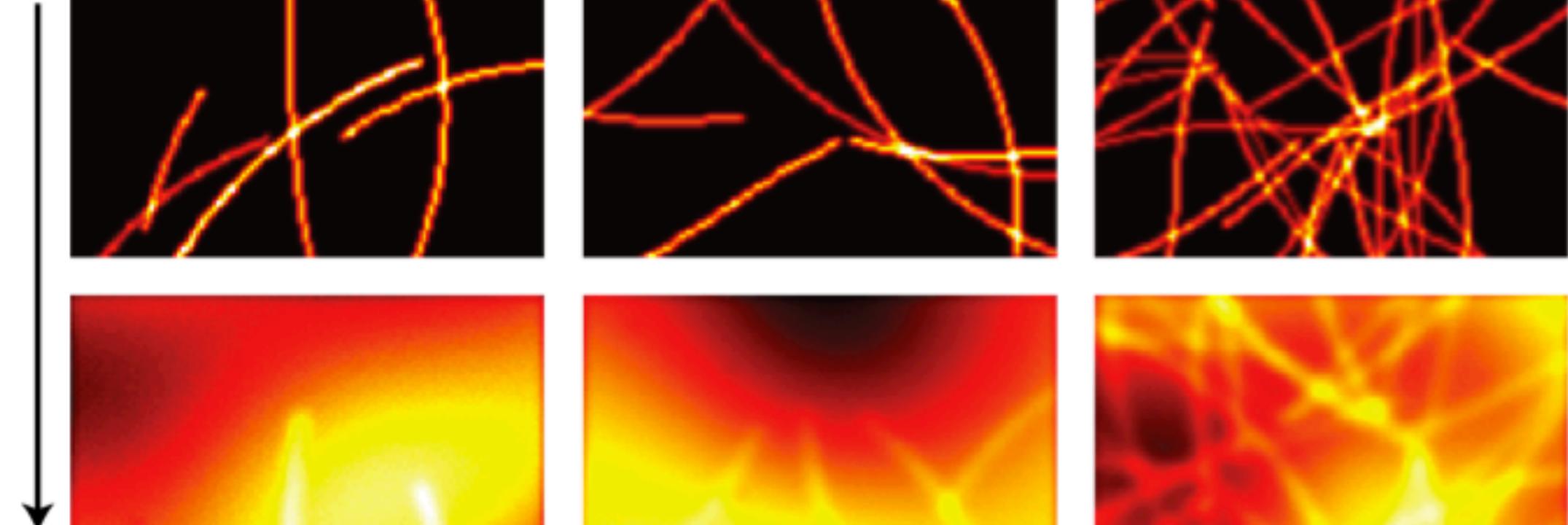
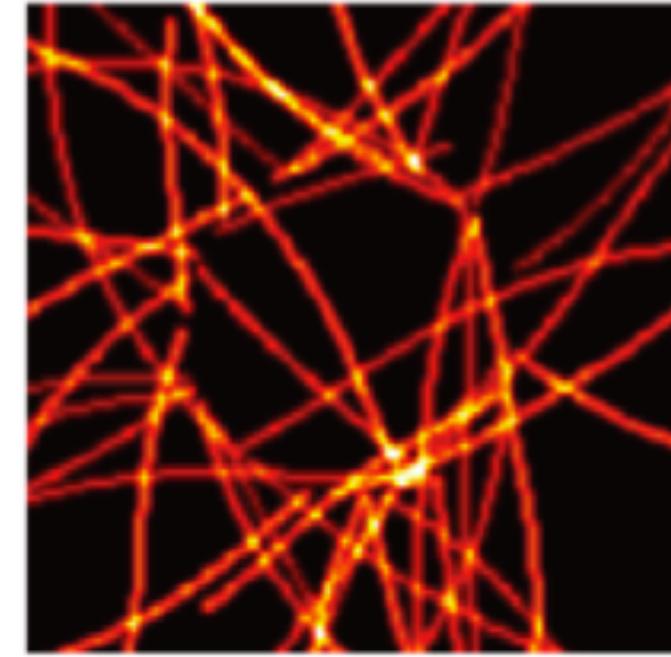
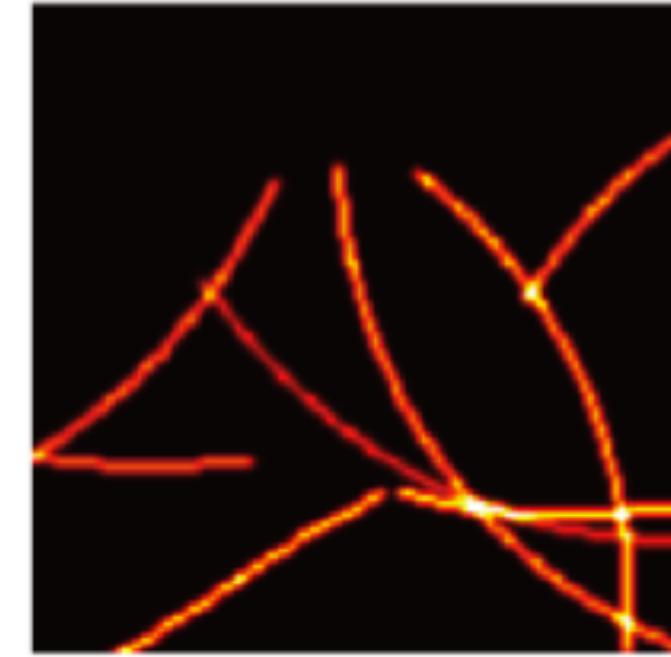
Works for upsampling too



Learning with synthetic models

Microtubules

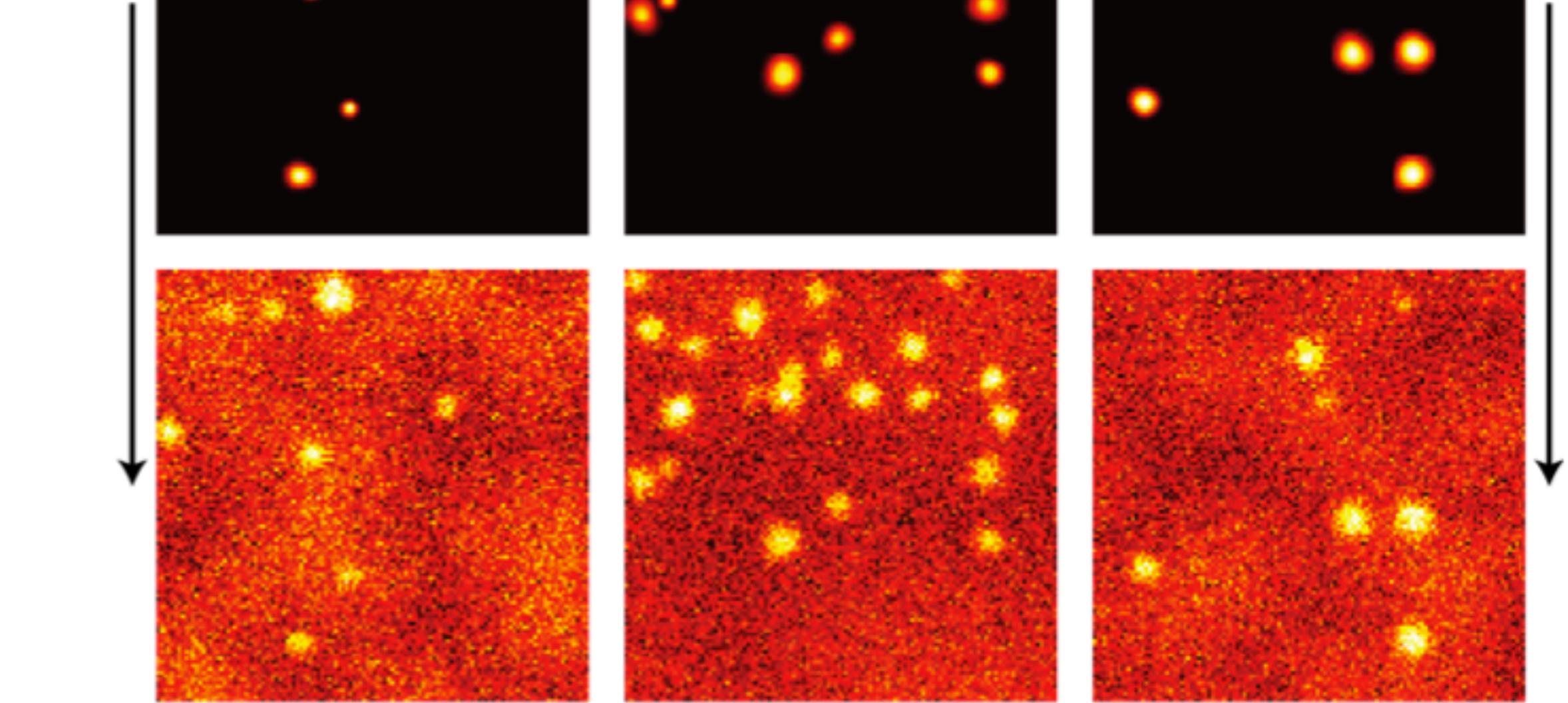
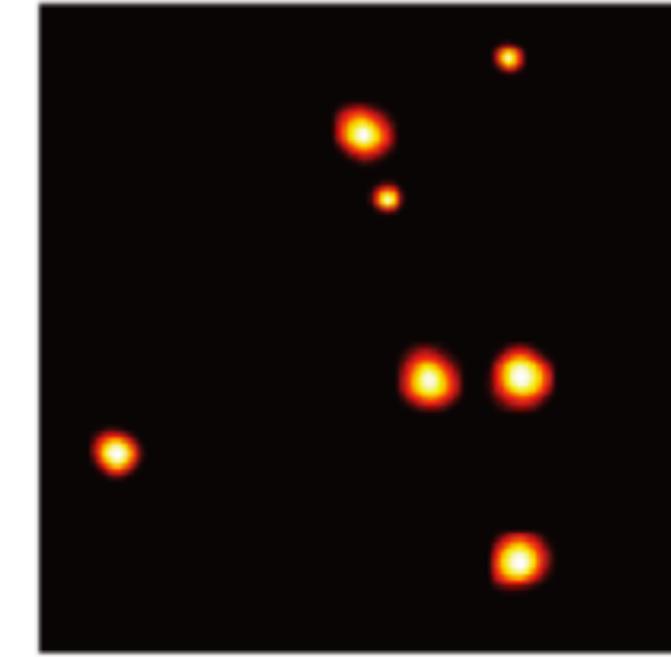
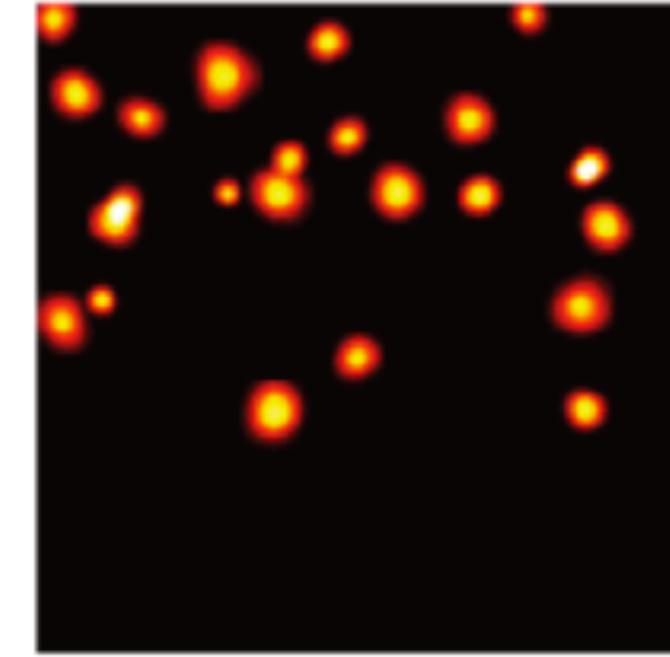
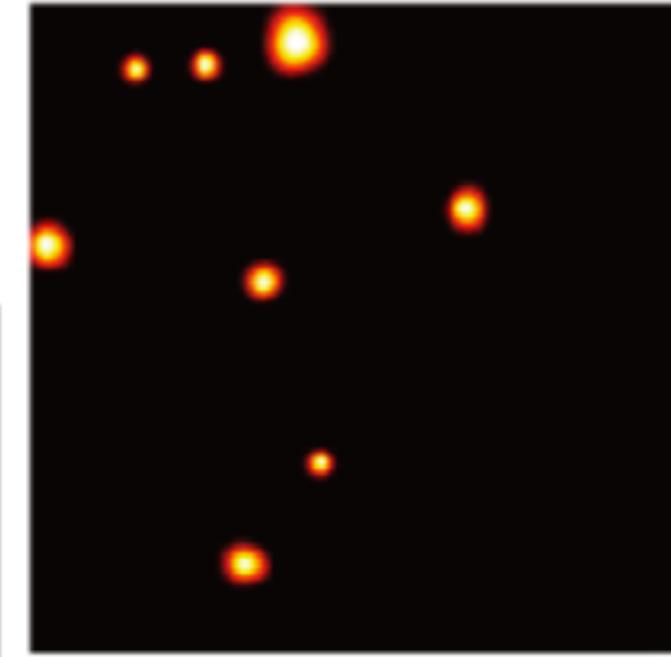
Y Ground Truth



X Synthetic image

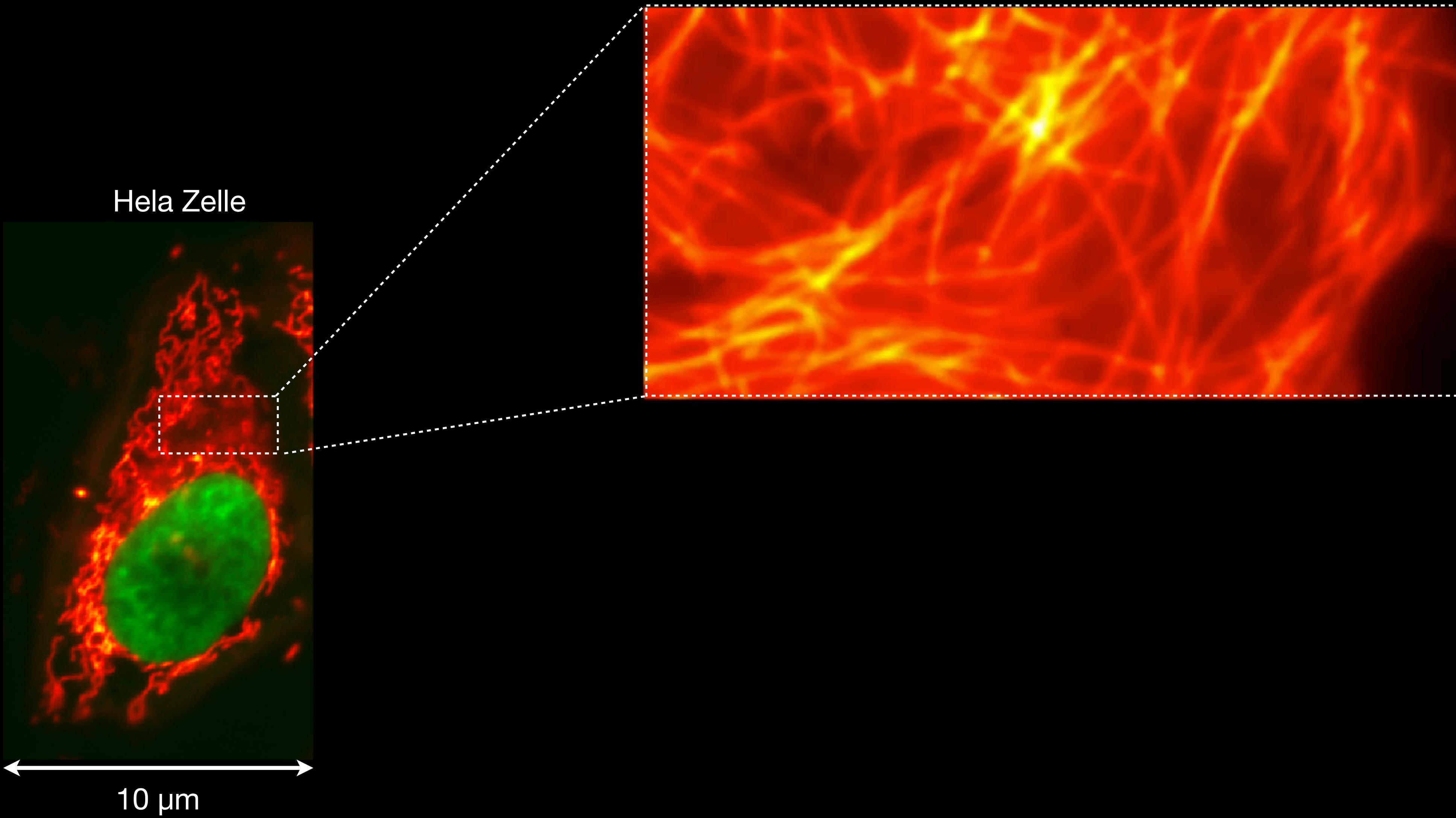
Granules

Y Ground Truth



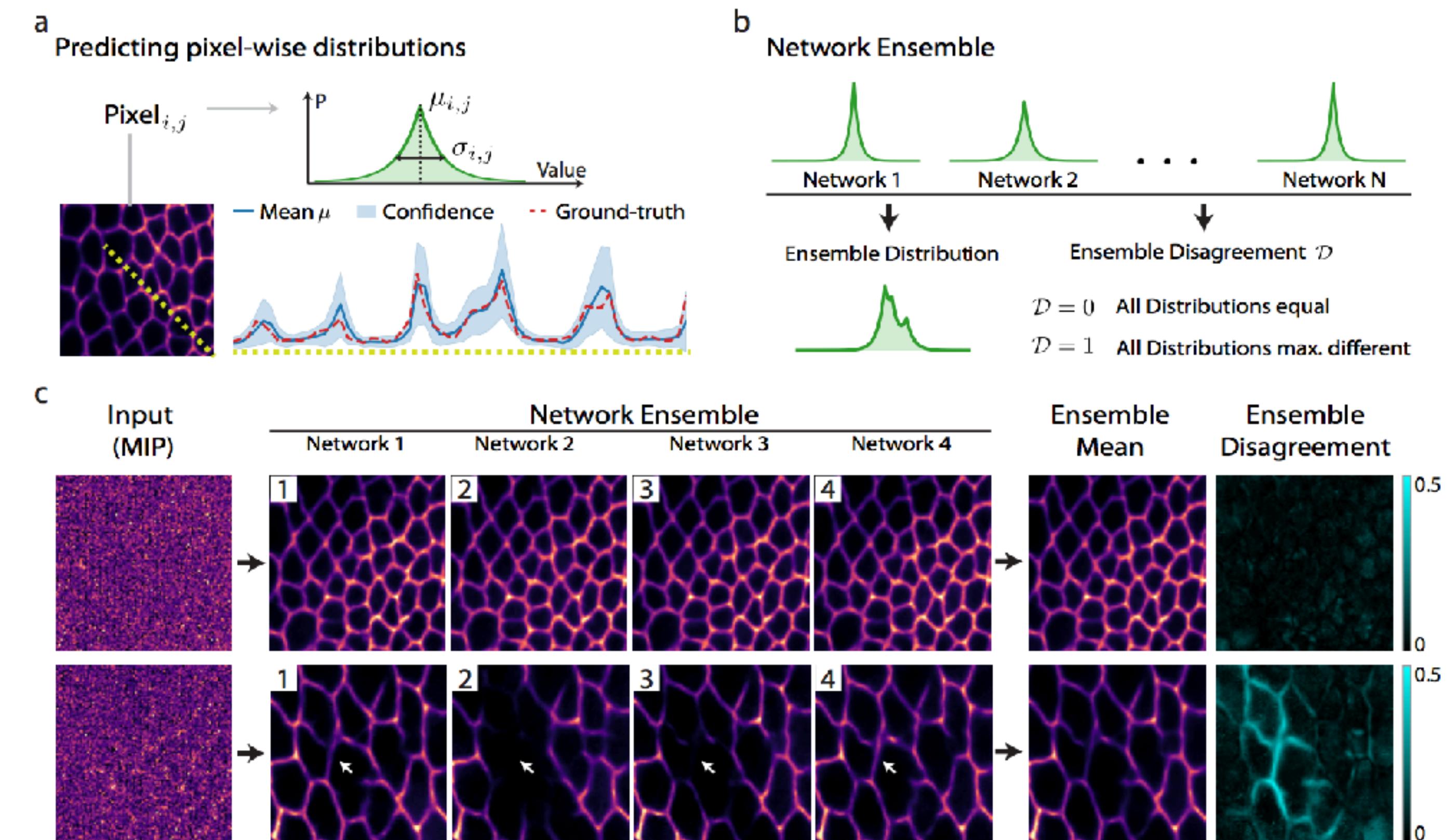
X Synthetic image

Learning with synthetic models



Challenges

- Interpretability (black box)
- Uncertainty quantification
- Out-of-Distribution detection



Recent Developments

- Analyzing Inverse Problems with Invertible Neural Networks
(Ardizzone, 2018)
- Noise2Noise: Learning Image Restoration without Clean Data
(Lehtinen, 2018)
- Deep Image Prior (Ulyanov, 2017)

Notebooks

day4/care/

- **denoising2D**
- denoising3D
- upsampling3D
- isotropic_reconstruction